Parity Odd Event Variables for Hadron Colliders

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Abstract

Parity odd functions of hadron collider events can be used to probe novel parity violating processes through asymmetries in their distributions. In this paper we present results used for the construction of such functions. Geometric Algebra algorithms are provided for the computational validation of our results.

Except where specific reference is made to the work of others, this work is original and has not been already submitted either wholly or in part to satisfy any degree requirement at this or any other university.

Contents

1	Introduction	2
2	Theory	2
3	Method	3
4	Results	4
5	Computational test of results using Geometric Algebra	15
6	Geometric perspective	21
7	Conclusion	23
8	Acknowledgements	23
\mathbf{A}	From events to event variables	24
в	Proofs for algorithms	24
С	Notation	26

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D Case 2 calculation for collision events

E Code

1 Introduction

Following the results of experiments by Wu et al in 1957 [1] which showed that the weak interaction violates parity, tests of parity violation have hitherto been limited, especially on LHC data [2]. Non-standard parity violating processes beyond the weak interactions can manifest themselves through asymmetries in distributions of event variables which are parity odd, applied to data generated by the LHC.

The data consist of events characterised by a set of real non space-like four-momenta. Given our methods are purely data-driven, at no point in constructing the variables do we rely on any theoretical model. Consequently, the method of this paper that follows from [3] aims to probe all sources of non-standard parity violation if any exist.

In this paper we specifically focus on the case of events which consist of two incoming and four outgoing objects, which can be two incoming protons and four outgoing jets. We aim to identify certain properties of the results obtained that can be used to generalise to N outgoing objects. The paper will present conditions for events to be non-chiral - see section 2 for the definition of non-chiral events - with the ambition of building event variables for different types of two to four events in future work.

In the following section we provide the theoretical background for our work, including necessary definitions and conventions. We then present the general method for this paper and our results for each type of events considered. A computational validation of the results follows, which utilizes the elegant power of Geometric Algebra. We give a geometric picture of our work before conluding in the last section. In the appendix, we provide a flowchart showing the method of this paper, proofs for the validity of our algorithms, some important notation used for the results in this paper and the explicit calculation of one of the cases considered below.

2 Theory

Let $S = \{V_i \mid i = [1, N]\}$ be the set of N event variables and $\Omega = \{e \mid e \text{ is chiral}\}$ the set of chiral events. An event is defined as chiral if after applying parity to it, it cannot be mapped onto itself by any combination of group elements from our choice of a symmetry group G. The symmetry group in this paper will be the Lorentz group $\times S_2 \times S_4$, where S_n is the permutation group of n elements. Note that S_2 only permutes incoming particles (if identical) and S_4 outgoing particles. As discussed with detail in [3], S must satisfy the properties of:

- Sufficiency: at least one V_i evaluates to a non-zero value for all $e \in \Omega$
- Necessity/irreducibility: removing any V_i would violate sufficiency
- **Reality**: $V_i : e \to \mathbb{R}$

- **Continuity:** small changes in energy or momenta to *e* should lead to small changes in the output of *V_i*
- Lorentz and permutation invariance: V_i should be Lorentz invariant and invariant under permuting identical objects such as jets or photons in incoming or outgoing states
- **Parity-odd**: all V_i change sign under parity $\vec{x} \rightarrow -\vec{x}$
- **Minimality**: if two sets satisfy all properties, we choose the one with the least number of elements.

Our ultimate aim is to construct the sets S_c and S_{nc} for $2 \to 4$ chiral, collision and non-collision events respectively. The classes of events called collision events \mathscr{E}^c and non-collision events \mathscr{E}^{nc} are given by definitions 2.23 and 2.26 in [3]. Roughly, a collision event has an initial state of two particles that can define a center of mass frame and in that frame the equal and opposite 3-momenta are non-zero. A non-collision event is an event that cannot satisfy these properties.

Intuitively, non-standard parity violating processes will push the average of at least one of the parity-odd event variables towards being very negative or very positive. This is because the variable will change sign if we evaluate it on a chiral event e or on the same event after applying parity to it $\mathscr{P}e$. Hence, if nature does not prefer a handedness for parity and produces equal numbers of left and right handed chiral events of the same process, then the output of the variable will have on average half of the time a positive sign and the other half a negative sign. Averaging over the '+1' and '-1', corresponding to outputs of positive and negative sign, would of course give 0. Now, if nature decides that it prefers a handedness for a given process, then for that class of chiral events the sign of at least one event variable will be the same throughout the sample of events and would drive the average significantly far from 0.

This is why we are not concerned about non-chiral events. Since they can be mapped onto themselves after parity by actions of the symmetry group, they evaluate to 0 on any parity odd function. Hence, they cannot be used to probe non-standard parity violating processes. The idea is that if we have a logic statement that is true for chiral events, then we can use it to construct event variables while ensuring that at least one of the event variables would evaluate to a non-zero value for any chiral event input. We need to enforce the last property so that any chiral event can be labelled left or right handed.

3 Method

The method to obtain S_c and S_{nc} is to first obtain a logic statement that is true when an event is non-chiral - see figure 5. Since we are concerned only with chiral events, we negate the latter logic statement. By having the logic statement which is true for chiral events, we can ensure that both S_c and S_{nc} satisfy the sufficiency condition. Using the latter logic statement that characterises which events from our class of events are chiral, we construct the variables V_i in each set (S_c, S_{nc}) and ensure these will satisfy all the conditions mentioned in section 2.

Given our symmetry group G, and the parity operation denoted by \mathscr{P} , a non-chiral event e is one for which there exists a set of group elements $\{g_1, ..., g_N\}$ such that $\mathscr{P}e = \hat{g}e$, where \hat{g} is the composition of the N group elements in $\{g_1, ..., g_N\}$. By going through all the possibilities for \hat{g} , we derive the logic statement that is true only for non-chiral events. We can then easily obtain the logic statement for chiral events by negation.

We start by deriving the logic statement which is true only for non-chiral collision events. Let the four-momenta of the incoming particles be denoted by p and q, while for the outgoing particles denoted by a, b, c, d. We can represent an event by e and a collision event by \hat{e} which follows from Lemma 2.27 in [3] as

$$e = \begin{bmatrix} m_p & m_q & m_a & m_b & m_c & m_d \\ \mathbf{p} & \mathbf{q} & \mathbf{a} & \mathbf{b} & \mathbf{c} & \mathbf{d} \\ p_z & q_z & a_z & b_z & c_z & d_z \end{bmatrix} \qquad \hat{e} = \begin{bmatrix} m_p & m_q & m_a & m_b & m_c & m_d \\ \mathbf{0} & \mathbf{0} & \mathbf{a} & \mathbf{b} & \mathbf{c} & \mathbf{d} \\ p & -p & a_z & b_z & c_z & d_z \end{bmatrix}$$

where we have aligned \vec{p} and \vec{q} with the positive and negative z-axis in the rest frame of $(p+q)^1$. Here we note $m_i \ge 0$, $\mathbf{j} \in \mathbb{C}$ and $j_z \in \mathbb{R}$ for j = a, b, c, d. Given any $g \in G$ has an inverse, we can say

$$g \cdot \hat{e} = \begin{pmatrix} \pi \\ \swarrow \\ yz \end{pmatrix} \cdot \mathscr{P} \cdot \hat{e} \Rightarrow \hat{e} \text{ is non-chiral}$$
(1)

Noting that

$$\begin{pmatrix} \pi \\ \ddots \\ yz \end{pmatrix} \cdot \mathscr{P} \cdot \hat{e} = \begin{bmatrix} m_p & m_q & m_a & m_b & m_c & m_d \\ \mathbf{0} & \mathbf{0} & -\mathbf{a}^* & -\mathbf{b}^* & -\mathbf{c}^* & -\mathbf{d}^* \\ p & -p & a_z & b_z & c_z & d_z \end{bmatrix}$$

we see that we can restrict the part of g that comes from the Lorentz group to only rotations by θ about the z-axis, since \vec{p} and \vec{q} are already fixed to their original state and must remain the same. Hence we can rewrite equation (1) as

$$\begin{pmatrix} \theta \\ \swarrow \\ xy \end{pmatrix} \cdot h \cdot \hat{e} = \begin{pmatrix} \pi \\ \swarrow \\ yz \end{pmatrix} \cdot \mathscr{P} \cdot \hat{e} \Rightarrow \hat{e} \text{ is non-chiral}$$
(2)

for any $h \in H = S_2 \times S_4$, giving a total of 48 cases for collision events.

4 Results

4.1 Collision events

We explicitly go through the first case and then state the final results for the rest of the cases. The logic statement that is true for non-chiral collision events is given in section 4.1.1. The explicit calculation for case 2 which is more involved is given in appendix D.

¹This means $\vec{p} + \vec{q} = 0$.

Case 1

In this first case $h = 1_{S_2} \cdot 1_{S_4}$ which represents the identity in both permutation groups. Following equation (2) we have

$$\begin{pmatrix} \pi \\ yz \end{pmatrix} \cdot \mathscr{P} \cdot \hat{e} = \begin{bmatrix} m_p & m_q \\ \mathbf{0} & \mathbf{0} \\ p & -p \end{bmatrix} \begin{vmatrix} m_a & m_b & m_c & m_d \\ |\mathbf{a}|e^{-i\alpha+i\pi+2i\pi n_a} & |\mathbf{b}|e^{-i\beta+i\pi+2i\pi n_b} & |\mathbf{c}|e^{-i\gamma+i\pi+2i\pi n_c} & |\mathbf{d}|e^{-i\delta+i\pi+2i\pi n_d} \\ a_z & b_z & c_z & d_z \end{vmatrix}$$

$$\begin{pmatrix} \theta \\ \ddots \\ xy \end{pmatrix} \cdot \mathbf{1}_{S_2} \cdot \mathbf{1}_{S_4} \cdot \hat{e} = \begin{bmatrix} m_p & m_q \\ \mathbf{0} & \mathbf{0} \\ p & -p \end{vmatrix} \begin{vmatrix} m_a & m_b & m_c & m_d \\ |\mathbf{a}|e^{i(\theta+\alpha)} & |\mathbf{b}|e^{i(\theta+\beta)} & |\mathbf{c}|e^{i(\theta+\gamma)} & |\mathbf{d}|e^{i(\theta+\delta)} \\ a_z & b_z & c_z & d_z \end{vmatrix}$$

Now we seek a logic statement that is true when the above 2 expressions are equal. Comparing each slot of our representation we get²

$$\begin{bmatrix} (|\mathbf{a}|=0) \lor (-\alpha + \pi + 2\pi n_a = \theta + \alpha) \end{bmatrix} \land \begin{bmatrix} (|\mathbf{b}|=0) \lor (-\beta + \pi + 2\pi n_b = \theta + \beta) \end{bmatrix} \land \\ \begin{bmatrix} (|\mathbf{c}|=0) \lor (-\gamma + \pi + 2\pi n_c = \theta + \gamma) \end{bmatrix} \land \begin{bmatrix} (|\mathbf{d}|=0) \lor (-\delta + \pi + 2\pi n_d = \theta + \delta) \end{bmatrix} \\ \Rightarrow \begin{bmatrix} (|\mathbf{a}|=0) \lor (\alpha = \frac{1}{2}(\pi - \theta) + n_a\pi) \end{bmatrix} \land \begin{bmatrix} (|\mathbf{b}|=0) \lor (\beta = \frac{1}{2}(\pi - \theta) + n_b\pi) \end{bmatrix} \land \\ \begin{bmatrix} (|\mathbf{c}|=0) \lor (\gamma = \frac{1}{2}(\pi - \theta) + n_c\pi) \end{bmatrix} \land \begin{bmatrix} (|\mathbf{b}|=0) \lor (\delta = \frac{1}{2}(\pi - \theta) + n_d\pi) \end{bmatrix}$$

Given all final state momenta have the same transverse plane angle modulo π , a general event following the above is one for which the four 3-momenta $\vec{a}, \vec{b}, \vec{c}, \vec{d}$ live on the same plane containing the beam axis and hence must satisfy

$$(\vec{i} \times \vec{j}) \cdot \vec{k} = 0$$

for $i, j, k = \{a, b, c, d, p\}, i \neq j \neq k$. This can be translated to a Lorentz invariant form using Lemma 2.35 and A.2.2 of [3]

$$\epsilon_{abpq} = \epsilon_{acpq} = \epsilon_{adpq} = \epsilon_{bdpq} = \epsilon_{bcpq} = \epsilon_{cdpq} = 0 \tag{3}$$

where a, b, c, d, p are 4-momenta and $\epsilon_{abpq} = \epsilon_{\mu\nu\sigma\rho}a^{\mu}b^{\nu}p^{\sigma}q^{\rho}$. This result generalises to N outgoing particles by writing

$$\epsilon_{ijpq} = 0$$

for i, j = all possible 2-pairs from {outgoing 4-momenta}, giving $\binom{N}{2}$ terms.

 $^{^2 \}mathrm{The} \lor$ symbol means 'or' and the \land symbol means 'and' in mathematical logic.

Case 2

The explicit calculation for this case can be found in appendix D. It serves as an example of how the calculations for the results presented throughout this paper have been produced. For the meaning of the notation used in the expression below and the rest of the paper see appendix C.

$$h = 1_{S_2} \cdot (ab)$$

$$(a^{2} = b^{2}) \wedge (G\binom{a-b, p+q}{p-q, p+q}) = 0) \wedge (G\binom{a-b, p+q}{a+b, p+q}) = 0)$$

$$\wedge \left[\left[(\Delta_{3}(a, p, q) = 0) \wedge (\Delta_{3}(b, p, q) = 0) \wedge (\Delta_{3}(c, p, q) \neq 0) \wedge (\Delta_{3}(d, p, q) \neq 0) \right]$$

$$\wedge \left[(\Delta_{3}(a, p, q) \neq 0) \wedge (\Delta_{3}(b, p, q) \neq 0) \wedge (\Delta_{3}(c, p, q) \neq 0) \wedge (\Delta_{3}(d, p, q) = 0) \right]$$

$$\wedge (G\binom{a-b, p+q}{c, p+q}) = 0 \right] \vee \left[(\Delta_{3}(a, p, q) \neq 0) \wedge (\Delta_{3}(b, p, q) \neq 0) \wedge (\Delta_{3}(d, p, q) \neq 0) \right]$$

$$\wedge (\Delta_{3}(c, p, q) = 0) \wedge (G\binom{a-b, p+q}{d, p+q}) = 0 \right] \vee \left[(\Delta_{3}(a, p, q) \neq 0) \wedge (\Delta_{3}(b, p, q) \neq 0) \wedge (\Delta_{3}(b, p, q) \neq 0) \right]$$

$$(\Delta_{3}(d, p, q) \neq 0) \wedge (\Delta_{3}(c, p, q) \neq 0) \wedge (G\binom{a-b, p+q}{c-d, p+q}) = 0 \right]$$

$$(4)$$

Cases 3-7

Cases 3-7 follow case 2 by symmetry with the element of S_4 in each one being (cd), (bc), (bd), (ac), (ad). These are 2-cycles in S_4 with the rest of the elements in 1-cycles. Each additional final state particle will double the number of subcases in this case, as can be seen from appendix D, making the generalisation of equation (4) to N outgoing particles a difficult task. However, one can exploit the apparent pattern in equation (4) to guess the additions that need to be made in each bracket for more outgoing particles. Cases like this one, for which h is guaranteed to be found in S_N for N greater than 4, are likely to generalise to more outgoing particles simply by comparison and without the need for an explicit calculation.

Cases 8-15

Cases 8-15 which are the 3-cycles of S_4 combined with 1_{S_2} were found to be sub-cases of case 1 and were thus discarded. We discard sub-cases since they do not give new information on how a state can be non-chiral. Concretely, we know that if all final state momenta lie in a plane the event is non-chiral. If a new case instructs us that an event is non-chiral if all final state momenta are zero, then that is already included in the information of all momenta lying in a plane and we can thus discard the new case.

Case 16

 $h = 1_{S_2} \cdot (ab)(cd)$

Remark: The group element in S_4 for this case is not found in S_3 , hence this case presents a new type of non-chirality with respect to the case of $2 \rightarrow 3$ collision events. This new information inhibits a straightforward generalisation of results for $2 \rightarrow N$ collision events, without the explicit calculation of such new type of cases. This remark applies to other cases presented below regardless of the type of events considered.

$$(a^{2} = b^{2}) \wedge (c^{2} = d^{2}) \wedge (G\binom{a - b, p + q}{p - q, p + q}) = 0) \wedge (G\binom{a - b, p + q}{a + b, p + q}) = 0)$$

$$\wedge (G\binom{c - d, p + q}{p - q, p + q}) = 0) \wedge (G\binom{c - d, p + q}{c + d, p + q}) = 0)$$

$$\wedge \left[\left[(\Delta_{3}(a, p, q) = 0) \wedge (\Delta_{3}(b, p, q) = 0) \wedge (\Delta_{3}(c, p, q) \neq 0) \wedge (\Delta_{3}(d, p, q) \neq 0) \right] \right]$$

$$\vee \left[(\Delta_{3}(c, p, q) = 0) \wedge (\Delta_{3}(d, p, q) = 0) \wedge (\Delta_{3}(a, p, q) \neq 0) \wedge (\Delta_{3}(b, p, q) \neq 0) \right]$$

$$\vee \left[(G\binom{a - b, p + q}{c + d, p + q}) = 0) \vee (G\binom{c - d, p + q}{b - p + q}) = 0) \vee (G\binom{a - b, p + q}{d - p + q}) = 0) \right]$$
(5)

Cases 17,18

Cases 17 and 18 are the other two elements of S_4 which consist of two 2-cycles and hence follow case 16 by symmetry.

Case 19

 $h = 1_{S_2} \cdot (dcba)$, where in our convention, this means $a \to b \to c \to d \to a$.

$$(a^{2} = b^{2} = c^{2} = d^{2}) \wedge (G\begin{pmatrix}a - b, p + q\\a + b, p + q\end{pmatrix}) = 0) \wedge (G\begin{pmatrix}b - c, p + q\\b + c, p + q\end{pmatrix}) = 0) \wedge (G\begin{pmatrix}c - d, p + q\\c + d, p + q\end{pmatrix}) = 0) \wedge (G\begin{pmatrix}a - b, p + q\\p - q, p + q\end{pmatrix}) = 0) \wedge (G\begin{pmatrix}b - c, p + q\\p - q, p + q\end{pmatrix}) = 0) \wedge (G\begin{pmatrix}c - d, p + q\\p - q, p + q\end{pmatrix}) = 0) \wedge (a = c) \wedge (b = d)$$
(6)

Cases 20-24

Cases 20 to 24 follow case 19 by symmetry as they are the 4-cycles of S_4 . However case 21 is the same as case 20, case 23 is the same as case 19 and case 24 is the same as case 22. Hence cases 21, 23 and 24 were discarded. One can find the explicit h for each of these cases in code form given in appendix E. The same applies for subsequent references to enumerated cases.

Case 25

$$h = \begin{pmatrix} \theta \\ \swarrow \\ xy \end{pmatrix} \cdot \begin{pmatrix} \pi \\ \Im \\ yz \end{pmatrix} \cdot (pq) \cdot 1_{S_4}$$

$$(p^{2} = q^{2}) \wedge (G\begin{pmatrix} a & p+q \\ p-q, p+q \end{pmatrix} = 0) \wedge (G\begin{pmatrix} b & p+q \\ p-q, p+q \end{pmatrix} = 0) \\ \wedge (G\begin{pmatrix} c & p+q \\ p-q, p+q \end{pmatrix} = 0) \wedge (G\begin{pmatrix} d & p+q \\ p-q, p+q \end{pmatrix} = 0)$$
(7)

The generalisation to N outgoing particles for this case is trivial. We simply augment the rest of the Gram determinants $G\begin{pmatrix} \cdot & , p+q \\ p-q, p+q \end{pmatrix} = 0$ with a \wedge symbol.

Case 26

$$h = \begin{pmatrix} \theta \\ xy \end{pmatrix} \cdot \begin{pmatrix} \pi \\ yz \end{pmatrix} \cdot (pq) \cdot (ab)$$

$$(p^{2} = q^{2}) \wedge (a^{2} = b^{2}) \wedge (G \begin{pmatrix} a+b, p+q \\ p-q, p+q \end{pmatrix} = 0)$$

$$\wedge (G \begin{pmatrix} a-b, p+q \\ a+b, p+q \end{pmatrix} = 0) \wedge (G \begin{pmatrix} c & p+q \\ p-q, p+q \end{pmatrix} = 0) \wedge (G \begin{pmatrix} d & p+q \\ p-q, p+q \end{pmatrix} = 0)$$

$$\wedge [(\Delta_{3}(a, p, q) = 0) \vee (\Delta_{3}(a+b, p, q) = 0) \vee (\Delta_{3}(a-b, p, q) = 0)]$$
(8)

Cases 27-31

Cases 27-31 follow case 26 by symmetry. Their elements are of the form $\begin{pmatrix} \theta \\ \ddots y \end{pmatrix} \cdot \begin{pmatrix} \pi \\ yz \end{pmatrix} \cdot (pq)$ and one of the elements of S_4 consisting of one 2-cycle and two 1-cycles. The generalisation to N outgoing particles follows by symmetry in the second line of equation (8) and gives $\binom{N}{2}$ cases.

Case 32

$$h = \begin{pmatrix} \theta \\ xy \end{pmatrix} \cdot \begin{pmatrix} \pi \\ yz \end{pmatrix} \cdot (pq) \cdot (dcb)$$

$$(p^{2} = q^{2}) \wedge (b^{2} = c^{2} = d^{2}) \wedge (G\begin{pmatrix} a & p+q \\ p-q, p+q \end{pmatrix}) = 0) \wedge (G\begin{pmatrix} b & p+q \\ p-q, p+q \end{pmatrix}) = 0)$$

$$\wedge (G\begin{pmatrix} c & p+q \\ p-q, p+q \end{pmatrix}) = 0) \wedge (G\begin{pmatrix} d & p+q \\ p-q, p+q \end{pmatrix}) = 0) \wedge (G\begin{pmatrix} b-c, p+q \\ b+c, p+q \end{pmatrix}) = 0)$$

$$\wedge (G\begin{pmatrix} c-d, p+q \\ c+d, p+q \end{pmatrix}) = 0) \wedge (G\begin{pmatrix} a & p+q \\ p-q, p+q \end{pmatrix}) = 0)$$

$$\wedge (\epsilon_{(b+d)cpq} = 0) \wedge (\epsilon_{(b+c)dpq} = 0) \wedge (\epsilon_{(c+d)bpq} = 0)$$
(9)

Cases 33-39

Cases 33-39 are the 3-cyles of S_4 combined with the non-trivial element of S_2 and follow case 32 by symmetry. However, cases 33, 36, 38 and 39 are included in previously considered cases and were thus discarded.

Case 40

$$h = \begin{pmatrix} \theta \\ \widehat{\chi y} \end{pmatrix} \cdot \begin{pmatrix} \pi \\ \widehat{y z} \end{pmatrix} \cdot (pq) \cdot (ab)(cd)$$

$$(p^{2} = q^{2}) \wedge (a^{2} = b^{2}) \wedge (c^{2} = d^{2})(G \begin{pmatrix} a + b, p + q \\ p - q, p + q \end{pmatrix}) = 0)$$

$$\wedge (G \begin{pmatrix} c + d, p + q \\ p - q, p + q \end{pmatrix}) = 0) \wedge [[(\Delta_{3} (a + b, p, q) = 0) \vee (\Delta_{3} (a - b, p, q) = 0)]$$

$$\vee [(\Delta_{3} (c + d, p, q) = 0) \vee (\Delta_{3} (c - d, p, q) = 0)]]$$
(10)

Cases 41,42

Cases 41 and 42 follow case 40 by symmetry with their elements being of the form $h = \begin{pmatrix} \theta \\ \ddots \\ xy \end{pmatrix} \cdot \begin{pmatrix} \pi \\ \ddots \\ yz \end{pmatrix} \cdot (pq)$ and an element of S_4 consisting of two 2-cycles.

Case 43

$$h = \begin{pmatrix} \theta \\ f \\ yz \end{pmatrix} \cdot \begin{pmatrix} \pi \\ yz \end{pmatrix} \cdot (pq) \cdot (dcba)$$

$$(p^{2} = q^{2}) \wedge (a^{2} = b^{2} = c^{2} = d^{2}) \wedge (G\begin{pmatrix} a - b, p + q \\ a + b, p + q \end{pmatrix} = 0) \wedge (G\begin{pmatrix} b - c, p + q \\ b + c, p + q \end{pmatrix} = 0)$$

$$\wedge (G\begin{pmatrix} c - d, p + q \\ c + d, p + q \end{pmatrix} = 0) \wedge (G\begin{pmatrix} a + b, p + q \\ p - q, p + q \end{pmatrix} = 0) \wedge (G\begin{pmatrix} b + c, p + q \\ p - q, p + q \end{pmatrix} = 0)$$

$$\wedge (G\begin{pmatrix} c + d, p + q \\ p - q, p + q \end{pmatrix} = 0) \wedge \left[(\Delta_{3} (a, p, q) = 0) \vee \left[(\epsilon_{(p+q)(a-c)pb} = 0) \wedge (\epsilon_{(p+q)(b-d)ap} = 0) \right] \right]$$

$$\vee \left[(\Delta_{3} (a - c, p, q) = 0) \wedge (\Delta_{3} (b - d, p, q) = 0) \wedge \left[(\Delta_{3} (a + b, p, q) = 0) \right] \right]$$

$$(11)$$

Cases 44-48

Cases 44 to 48 follow case 43 by symmetry and their elements are of the form $h = \begin{pmatrix} \theta \\ \ddots \\ yz \end{pmatrix} \cdot \begin{pmatrix} \pi \\ yz \end{pmatrix} \cdot (pq)$ and one 4-cycle element of S_4 .

4.1.1 Condition for a collision event to be non-chiral

A collision event is non-chiral iff the logic statement - formed by combining all the logic statements in equations (3)-(11), as well as those that follow by symmetries, with \lor - is true.

4.2 Non-collision events with at least one of p and q being massive

Using corollary 3.3 of [3], a non-collision event with at least one of p and q being massive can be represented by

$$e = \left\{ \begin{array}{c|cccc} p & q & a & b & c & d \\ \hline m_p & m_q & m_a & m_b & m_c & m_d \\ \vec{0} & \vec{0} & \vec{a} & \vec{b} & \vec{c} & \vec{d} \end{array} \right\}.$$
 (12)

The action of parity on this representation gives

$$\mathscr{P} \cdot e = \left\{ \begin{array}{c|cccc} p & q & a & b & c & d \\ \hline m_p & m_q & m_a & m_b & m_c & m_d \\ \vec{0} & \vec{0} & -\vec{a} & -\vec{b} & -\vec{c} & -\vec{d} \end{array} \right\},\tag{13}$$

from which we can see that our symmetry group can exclude boosts and permutations of p with q. Hence for non-collision events we only consider global general rotations R combined with the S_4 permutation group on the final state momenta. We will explicitly go through case 1 with $h = 1_{S_4} \cdot R$ and state the result of all others.

Case 1

$$h = 1_{S_4} \cdot R$$

$$1_{S_4} \cdot R \cdot \mathscr{P} \cdot e = \left\{ \begin{array}{c|ccc} p & q & a & b & c & d \\ \hline m_p & m_q & m_a & m_b & m_c & m_d \\ \vec{0} & \vec{0} & -R\vec{a} & -R\vec{b} & -R\vec{c} & -R\vec{d} \end{array} \right\},\tag{14}$$

For non-chiral events we require equation (14) to be equal to equation (12). This forces the condition $(\vec{a} = -R\vec{a}) \wedge (\vec{b} = -R\vec{b}) \wedge (\vec{c} = -R\vec{c}) \wedge (\vec{d} = -R\vec{d})$. A general event following the latter condition has all four final state momenta lying in a common plane which is perpendicular to the rotation axis of R, where R must represent a π rotation, and any one of them can be the null vector. This can be expressed in a Lorentz invariant way as follows

$$\epsilon_{abc(p+q)} = \epsilon_{abd(p+q)} = \epsilon_{bcd(p+q)} = \epsilon_{acd(p+q)} = 0 \tag{15}$$

The generalisation to N final state particles is trivial and gives $\binom{N}{3} \epsilon$ terms. To see equation (15) consider the following. If \vec{a} , \vec{b} , \vec{c} are to be in the same plane we require $(\vec{a} \times \vec{b}) \cdot \vec{c} = 0$. Note that $(p+q) = [m_p + m_q, 0, 0, 0]$ and $(\vec{a} \times \vec{b}) \cdot \vec{c} = 0 \iff \epsilon_{ijk} a_i b_j c_k = 0$, where $i, j, k = \{1, 2, 3\}$. Since (p+q) is only non-zero for the index 0, we can augment it to $\epsilon_{ijk} a_i b_j c_k = 0$ and switch to Greek indices that run from 0 to 3 as $\epsilon_{abc(p+q)} = \epsilon_{\mu\nu\sigma\rho} a^{\mu} b^{\nu} c^{\sigma} (p+q)^{\rho} = 0 \iff \epsilon_{ijk} a_i b_j c_k = 0$. In this last step we have used the property of the ϵ tensor that is non-zero only when all the indices are different.

Case 2

h = (ab)R

$$(a^{2} = b^{2}) \wedge a \neq b \wedge (G\begin{pmatrix}a, p+q\\a, p+q\end{pmatrix}) = G\begin{pmatrix}b, p+q\\b, p+q\end{pmatrix}) \wedge (G\begin{pmatrix}a, p+q\\c, p+q\end{pmatrix}) = G\begin{pmatrix}b, p+q\\d, p+q\end{pmatrix} = G\begin{pmatrix}b, p+q\\d, p+q\end{pmatrix})$$
(16)

To generalise this expression to N final state particles, we just need to extend the second line in an obvious pattern so that it consists of N - 2 terms.

Cases 3-7

Cases 3-7 have an h = gR with g being an element of S_4 that permutes two final state objects and leaves the other two unaffected. These follow equation (16) by symmetry.

Case 8

h = (ab)(cd)R

$$(a^{2} = b^{2}) \wedge (c^{2} = d^{2}) \wedge (G\binom{a, p+q}{a, p+q}) = G\binom{b, p+q}{b, p+q}) \wedge (G\binom{c, p+q}{c, p+q}) = G\binom{d, p+q}{d, p+q}) \wedge [[((a+b)^{2} = 4a^{2} = 4b^{2}) \wedge ((c+d)^{2} = 4c^{2} = 4d^{2})] \vee [(G\binom{a+b, p+q}{c-d, p+q}) = 0) \wedge (c \neq d)]]$$
(17)

Cases 9-10

These cases have an h = gR where g is an element of S_4 that consists of two 2-cycles and their statement follows equation (17) by symmetry.

Cases 11-18

These cases have h = gR with $g \in S_4$ being a 3-cycle. They are all subsets of case 1 and were thus discarded.

Case 19

h = (abcd)R

$$(a^{2} = b^{2} = c^{2} = d^{2}) \wedge (G\binom{a, p+q}{a, p+q}) = G\binom{b, p+q}{b, p+q} = G\binom{c, p+q}{c, p+q} = G\binom{d, p+q}{d, p+q}) \wedge (G\binom{a-c, p+q}{b-d, p+q}) = 0)$$
(18)

Cases 20-24

Cases 20-24 have an h = gR with g being a 4-cycle of S_4 and their statement follows equation (18) by symmetry.

4.2.1 Condition for a non-collision event - with at least one of p and q being massive - to be non-chiral

A non-collision event with at least one of p and q being massive is non-chiral iff the logic statement - formed by combining all the logic statements in equations (15)-(18), as well as those that follow by symmetries, with \lor - is true.

4.3 Non-collision events with both p and q being massless

Following section 3.3 of [3], a non-collision event with both incoming objects being massless can be represented in the (a+b+c+d) rest frame with p and q aligned with the z-axis as

$$\hat{e} = \begin{bmatrix} 0 & 0 & | & m_a & m_b & m_c & m_d \\ 0 & 0 & | & \mathbf{a} & \mathbf{b} & \mathbf{c} & \mathbf{d} \\ p_z & q_z & | & a_z & b_z & c_z & d_z \end{bmatrix} \quad \text{with} \quad \begin{pmatrix} p_z, q_z, m_a, m_b, m_c, m_d \ge 0, \\ p_z + q_z > 0, \\ \mathbf{a}, \mathbf{b}, \mathbf{c}, \mathbf{d} \in \mathbb{C}, \\ \mathbf{a} + \mathbf{b} + \mathbf{c} + \mathbf{d} = 0, \\ a_z, b_z, c_z, d_z \in \mathbb{R} \text{ and } a_z + b_z + c_z + d_z = 0 \end{pmatrix}$$
(19)

We would like to act with a symmetry group on $R_y(\pi) \cdot \mathscr{P} \cdot e$ and check when it is equal to e. Note that $R_y(\pi)$ reduces the amount of minus signs we have to work with and its inverse always exists, in order to absorb it into the group element that would take the parity inverted e to e. Given the form of $R_y(\pi) \cdot \mathscr{P} \cdot e$ is

$$R_y(\pi) \cdot \mathscr{P} \cdot e = \begin{bmatrix} 0 & 0 & m_a & m_b & m_c & m_d \\ 0 & 0 & \mathbf{a}^* & \mathbf{b}^* & \mathbf{c}^* & \mathbf{d}^* \\ p_z & q_z & a_z & b_z & c_z & d_z \end{bmatrix}.$$
 (20)

we can see that our symmetry group can exclude boosts, (pq) swaps and any rotation other than about the z-axis, otherwise p and q which are already matched to e will lose this matching. Hence our symmetry group is $R_z(\theta) \cdot g$ where g is an element of S_4 that permutes the final state momenta a,b,c and d. We will explicitly go through case 1 and then state the result for the remaining cases.

We note that an event with $(a + b + c + d)^2 = 0$ has all vectors being massless and pointing in the same spatial direction. Hence there are only two independent 4-momenta in the event which cannot form a Lorentz invariant pseudoscalar (at least four are needed). This means an event with

$$(a+b+c+d)^2 = 0$$
(21)

is always non-chiral.

Case 1

In the first case we have $h = R_z(\theta) \cdot 1_{S_4}$. The explicit form of $e = h \cdot R_y(\pi) \cdot \mathscr{P} \cdot e$ can be written as³

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \\ p_z & q_z \end{bmatrix} \begin{pmatrix} m_a & m_b & m_c & m_d \\ |\mathbf{a}|e^{i(\alpha-2\pi n_a)} & |\mathbf{b}|e^{i(\beta-2\pi n_b)} & |\mathbf{c}|e^{i(\gamma-2\pi n_c)} & |\mathbf{d}|e^{i(\delta-2\pi n_d)} \\ a_z & b_z & c_z & d_z \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} 0 & 0 & m_a & m_b & m_c & m_d \\ 0 & 0 & |\mathbf{a}|e^{i(\theta-\alpha)} & |\mathbf{b}|e^{i(\theta-\beta)} & |\mathbf{c}|e^{i(\theta-\gamma)} & |\mathbf{d}|e^{i(\theta-\delta)} \\ p_z & q_z & a_z & b_z & c_z & d_z \end{bmatrix}$$
(22)

 $\Rightarrow ((\mathbf{a} = 0) \lor (\alpha = \theta - \alpha + 2\pi n_a)) \land ((\mathbf{b} = 0) \lor (\beta = \theta - \beta + 2\pi n_b)) \land ((\mathbf{c} = 0) \lor (\gamma = \theta - \gamma + 2\pi n_c)) \land ((\mathbf{d} = 0) \lor (\delta = \theta - \delta + 2\pi n_d))$

$$\Rightarrow ((\mathbf{a} = 0) \lor (\alpha = \frac{\theta}{2} + \pi n_a)) \land ((\mathbf{b} = 0) \lor (\beta = \frac{\theta}{2} + \pi n_b)) \land ((\mathbf{c} = 0) \lor (\gamma = \frac{\theta}{2} + \pi n_c)) \land ((\mathbf{d} = 0) \lor (\delta = \frac{\theta}{2} + \pi n_d))$$

This is telling us that $\vec{a}, \vec{b}, \vec{c}, \vec{d}, \vec{p}, \vec{q}$ all lie in the same plane which includes the z-axis and has an angle $\frac{\theta}{2}$ to the x-axis. Any of the vectors can be the null vector, but not \vec{p} and \vec{q} simultaneously. We thus want relationships of the form $(\vec{a} \times \vec{b}) \cdot (\vec{p} + \vec{q}) = 0$ in the (a+b+c+d) rest frame. If we let $\Sigma = (a + b + c + d)$, this can be written as follows

$$\epsilon_{ab(p+q)\Sigma} = \epsilon_{ac(p+q)\Sigma} = \epsilon_{ad(p+q)\Sigma} = \epsilon_{bc(p+q)\Sigma} = \epsilon_{bd(p+q)\Sigma} = \epsilon_{cd(p+q)\Sigma} = 0$$
(23)

This can be generalised to N outgoing objects by extending the above expression to all pairs in the first 2 slots of ϵ .

Case 2

$$h = R_z(\theta) \cdot (ab)$$

$$(a^{2} = b^{2}) \wedge (G\begin{pmatrix} a - b, \Sigma \\ p + q, \Sigma \end{pmatrix}) = 0 \wedge (\Delta_{2} (a, \Sigma) = \Delta_{2} (b, \Sigma))$$

$$\wedge (G\begin{pmatrix} a, \Sigma \\ c, \Sigma \end{pmatrix}) = G\begin{pmatrix} b, \Sigma \\ c, \Sigma \end{pmatrix}) \wedge (G\begin{pmatrix} a, \Sigma \\ d, \Sigma \end{pmatrix}) = G\begin{pmatrix} b, \Sigma \\ d, \Sigma \end{pmatrix})$$
(24)

Cases 3-7

These have $h = R_z(\theta) \cdot g$ with g being a 2-cycle of S_4 with the other two elements left unchanged. They follow equation (24) by symmetry. Extending these statements to N outgoing objects requires the extension of the second line of equation (24) in a straight-forward way giving N-2 terms rather than 2.

³The question mark on the equality sign is asking: 'What condition must be met for this equality to hold?'.

Case 8

 $h = R_z(\theta) \cdot (ab)(cd)$

$$(a^{2} = b^{2}) \wedge (G\begin{pmatrix} a - b, \Sigma \\ p + q, \Sigma \end{pmatrix}) = 0 \wedge (\Delta_{2} (a, \Sigma) = \Delta_{2} (b, \Sigma))$$

$$\wedge (c^{2} = d^{2}) \wedge (G\begin{pmatrix} c - d, \Sigma \\ p + q, \Sigma \end{pmatrix}) = 0 \wedge (\Delta_{2} (c, \Sigma) = \Delta_{2} (d, \Sigma))$$

$$\wedge G\begin{pmatrix} a - b, \Sigma \\ c + d, \Sigma \end{pmatrix} = 0$$
(25)

Cases 9-10

These cases have $h = R_z(\theta) \cdot g$ with g an element of S_4 consisting of two 2-cycles. They follow equation (25) by symmetry.

Cases 11-24

These cases have $h = R_z(\theta) \cdot g$ with $g \in S_4$ a 3-cycle for cases 11-18 and a 4-cycle for cases 19-24. They were found to be sub-cases of previously included cases and were thus discarded.

4.3.1 Condition for a non-collision event with both p and q being massless to be non-chiral

A non-collision event with both p and q being massless is non-chiral iff the logic statement - formed by combining the logic statements in equations (21)-(25) as well as those that follow by symmetries, with \vee - is true.

4.4 Non-collision events with p = q = 0

We can no longer use p and q and we thus orient our coordinate system with the z-axis aligned with the momentum of particle a. We also work in the (a+b+c+d) rest frame as in the previous section and the results follow directly from section 3.3.1 onwards in [3]. Note that when $a_z = 0$, which implies $\vec{a} = 0$ in our choice of coordinate system, we cannot form a pseudoscalar and those cases are non-chiral leaving the z-axis well defined for the rest of the cases considered.

Our setup can be represented by

$$e = \begin{bmatrix} m_a & m_b & m_c & m_d \\ 0 & |\mathbf{b}|e^{i(\beta - 2\pi n_b)} & |\mathbf{c}|e^{i(\gamma - 2\pi n_c)} & |\mathbf{d}|e^{i(\delta - 2\pi n_d)} \\ b_z & c_z & d_z \end{bmatrix}$$
(26)

and so we can quote the result of [3] in corollary 4.6, with the mapping $p+q \rightarrow a$, $\Sigma \rightarrow (a+b+c+d)$, $a \rightarrow b$, $b \rightarrow c$, $c \rightarrow d$. A non-collision event with p = q = 0 is non-chiral iff

$$G\begin{pmatrix}a, \Sigma\\a, \Sigma\end{pmatrix} = 0$$

$$(a + b + c + d)^{2} = 0$$

$$(a + b + c + d)^{2} = 0$$

$$(b^{2} = c^{2}) \wedge \left(G\begin{pmatrix}b - c, \Sigma\\a, \Sigma\end{pmatrix} = 0\right) \wedge (\Delta_{2} (b, \Sigma) = \Delta_{2} (c, \Sigma))$$

$$(c^{2} = d^{2}) \wedge \left(G\begin{pmatrix}c - d, \Sigma\\a, \Sigma\end{pmatrix} = 0\right) \wedge (\Delta_{2} (c, \Sigma) = \Delta_{2} (d, \Sigma))$$

$$(d^{2} = b^{2}) \wedge \left(G\begin{pmatrix}d - b, \Sigma\\a, \Sigma\end{pmatrix} = 0\right) \wedge (\Delta_{2} (d, \Sigma) = \Delta_{2} (b, \Sigma))$$

$$(d^{2} = b^{2}) \wedge \left(G\begin{pmatrix}d - b, \Sigma\\a, \Sigma\end{pmatrix} = 0\right) \wedge (\Delta_{2} (d, \Sigma) = \Delta_{2} (b, \Sigma))$$

where the first line comes from the case when $a_z = 0$.

5 Computational test of results using Geometric Algebra

In this section we describe the method used to test the above results. We randomly generate $2 \rightarrow 4$ events and use geometric algebra to label whether the event is chiral or non-chiral. We then evaluate the logic statements derived above - which are true for non-chiral states - on these events and check that the output is true for non-chiral events and false for chiral events.

The motivation to use geometric algebra (GA) rather than the standard linear algebra is that with GA the geometry is manifest and manipulation of mathematical objects becomes almost trivial, while also boosting the efficiency of computations.

Since from our choice of setup all types of events exclude boosts from their symmetry group, in this section we are working with 3-vectors and do not involve any boost transformations.

5.1 Basics of geometric algebra

There are numerous sources for an introduction to geometric algebra [4],[5], but here we sketch the very basics for 3D Euclidean geometry.

Define the geometric product of two vectors using the usual dot product and outer product as

$$uv = u \cdot v + u \wedge v \tag{28}$$

The outer product forms a bivector and has the following defining properties

$$u \wedge v = -v \wedge u \tag{29}$$

$$u \wedge (v+w) = u \wedge v + u \wedge w \tag{30}$$

The bivector $u \wedge v$ can be visualized as the directed plane formed by the vectors u and v - see Figure 1. Let our vector space be spanned by e_1, e_2, e_3 . We note the following important results



Figure 1: The outer product. The outer or wedge product of a and b returns a directed area element of area $|a||b|\sin(\theta)$. The orientation of the parallelogram is defined by whether the circuit a, b, a, b is right-handed (anticlockwise) or left-handed (clockwise). Interchanging the order of the vectors reverses the orientation and introduces a minus sign in the product. The figure is taken from [4].

$$e_i e_j = e_i \wedge e_j \tag{31}$$

$$e_i e_j = e_i \wedge e_j \tag{31}$$
$$e_i e_j = -e_j e_i \tag{32}$$

$$(e_i e_j)^2 = -1 \tag{33}$$

Equation (33) is a profound property of bivectors that behave as imaginary numbers and can be used to generalise quaternions.

A rotor is an object characterised by an angle θ and a bivector B which are enough information to fully parameterise a rotation⁴. We define a rotor as

$$R = e^{-\frac{\theta}{2}B} = \cos\left(\frac{\theta}{2}\right) - B\sin\left(\frac{\theta}{2}\right) \tag{34}$$

⁴Boosts - not used in this paper - can be represented using the spacetime algebra (STA) with basis vectors $\gamma_{\mu} \cdot \gamma_{\nu} = \eta_{\mu\nu}$ as $R = e^{\alpha \gamma_i \gamma_0}$, for a boost in the γ_i direction and rapidity α . The transformation with R is the same as for rotations, see [4].

which through the operation RvR^{\dagger} takes the vector v and rotates it by an angle θ in the directed plane described by B. We define the dagger operator on a bivector to result in the reverse bivector. For example $(e_1e_2)^{\dagger} = (e_2e_1)$. If we have 2 vectors a and b and we would like to rotate a to b then we construct the appropriate rotor R as described⁵ in Figure 2, resulting in

$$n = \frac{a+b}{\|a+b\|}$$
$$R = bn \tag{35}$$



Figure 2: A rotation from a to b. The vector a is rotated onto b by first reflecting in the plane perpendicular to n, and then in the plane perpendicular to b. The vectors a, b and n all have unit length. Figure taken from [4].

5.2 Algorithm for collision events

The purpose of the algorithm is to take in a randomly generated event and label it either chiral or non-chiral, according to the definitions given in section 2.

For a collision event we have p aligned with the z-axis and q = -p, as we are working in the (p+q) rest frame. Let an event be described by S = [p, q, a, b, c, d] and define $RSR^{\dagger} = [RpR^{\dagger}, RqR^{\dagger}, ..., RdR^{\dagger}]$, where all vectors are to be understood as 3-vectors. We can write the algorithm, that does not incorporate permutations, algebraically as follows

 $Steps^6$:

⁵In geometric algebra the reflection of a into the plane perpendicular to n is done simply by $a \rightarrow -nan$.

⁶Intuition: p, q, a_{12} define a plane in which we rotate by π using $R = a_{12}e_3$. Note that it does not matter here if we use a_{12} from S or S_1 since we are doing a π rotation.

1) Parity inversion: $S \to S_1 = -S$.

2) Project a into the 1-2 plane and normalise: $a_{12} = \frac{a-a_3}{|a-a_3|}$.

3) Map p, q, a back to their original state with $R = a_{12}e_3$: $S_1 \to S_2 = RS_1R^{\dagger}$.

4) If $S_2 = S$ output 'non-chiral', otherwise output 'chiral'.

If a_{12} is zero, repeat the algorithm with b. If b_{12} is zero, then repeat the algorithm with c, and if c_{12} is zero, output 'non-chiral' and terminate. The idea is that after we map p, q and a we have no subspace in which to perform any other rotations and so we reach the step where we should check if the rest of the particles mapped back to their original state. With permutations the algorithm becomes more complex but the idea of subspaces remains and can be found in appendix E in code form, where we use the Clifford library [6]. The proof that the general algorithm covers all possible inputs is given in appendix B.1.

5.3 Results for collision events

Now that the algorithm has labeled collision events chiral or non-chiral, we can evaluate the logic statement in section 4.1.1 on these states and expect an output of true when we use the non-chiral states and false when we use the chiral ones. As with the rest of the cases discussed below, we generate 1000 states of each type and check the appropriate logic statement. The results are presented in figure 3.



Figure 3: (a) Non-chiral and (b) chiral states evaluated on the logic statement that is true when a collision event is non-chiral. This logic statement can be found in section 4.1.1.

5.4 Algorithm for non-collision events with at least one of p and q being massive

For a non-collision event with at least one of p and q being massive, we have p, q both stationary. Under parity p and q are invariant so we can exclude boosts and only work with general rotations. Below we describe the algorithm for the case where no permutations are available. The algorithm that includes permutations can be found in appendix E in code form, where again we use the Clifford library [6]. The proof for the covering of the general algorithm can be found in appendix B.2.

 $Steps^7$:

1) Parity inversion: $S \to S_1 = -S$.

2) Map a and b back to their original state with $R = \frac{a \wedge b}{|a \wedge b|}$: $S_1 \to S_2 = RS_1 R^{\dagger}$.

3) If $S_2 = S$ output 'non-chiral', otherwise output 'chiral'.

If a, b are collinear, repeat the algorithm with a, c. If the latter are collinear output 'non-chiral' and terminate, since 3 out of 4 final state particles are collinear.

5.5 Results for non-collision events with at least one of p and q being massive

We test the logic statement given in section 4.2.1 with 1000 randomly generated chiral events and 1000 randomly generated non-chiral events that are labelled by the generalisation of the algorithm described above. The results are the same as shown in figure 3.

5.6 Non-collision events with both p and q being massless

For non-collision events with both p and q being massless we test the logic statement given in section 4.3.1. We again present the algorithm for the case where no permutations are available, while the full algorithm is given in appendix E in code form. In section B.3 we give the proof that the generalisation of the algorithm below covers all possible inputs.

Steps⁸:

⁷Intuition: For 2 final state particles, parity keeps them in the same original plane, hence a π rotation in that plane brings them back to their original state. A π rotation is achieved with $R = e^{\frac{\pi}{2}B} = B$, where $B = \frac{a \wedge b}{|a \wedge b|}$. Step 4 says that if a, b, c are collinear we can always do a π rotation in the a - d plane and map everything back, so those states are non-chiral.

⁸Intuition: Once we map p and q back to their original state with R_1 , we can only do rotations in the plane perpendicular to p and q. Note step 2 fixed the 3^{rd} component of a and $a_{rot,12}$ is extracted from S_2 .

1) Parity inversion: $S \to S_1 = -S$.

2) Map p and q back to themselves with $R_1 = e_1 e_3 : S_1 \to S_2 = R_1 S_1 R_1^{\dagger}$.

3) In the 1-2 plane, rotate a to its original state with $R_2 = a_{12}a_{rot,12}: S_2 \rightarrow S_3 = R_2S_2R_2^{\dagger}$.

4) If $S_3 = S$ output 'non-chiral', otherwise output 'chiral'.

5.7 Results for non-collision events with both p and q being massless

We follow the same test procedure as in the previous sections. The results follow what is expected from the logic statement in section 4.3.1 and match what is shown in figure 3.

5.8 Non-collision events with p = q = 0

For non-collision events with both p and q being 0 we test the logic statement given in equation (27). The algorithm for the case where no permutations are available is presented below and the full algorithm is given in appendix E in code form. The proof that the general algorithm covers all possible inputs can be found in appendix B.4.

Steps⁹:

1) Parity inversion: $S \to S_1 = -S$.

2) Map *a* back to its original state with $R_1 = e_1 e_3 : S_1 \to S_2 = R_1 S_1 R_1^{\dagger}$.

3) In the 1-2 plane, rotate b to its original state with $R_2 = b_{12}b_{rot,12}: S_2 \rightarrow S_3 = R_2S_2R_2^{\dagger}$.

4) If $S_3 = S$ output 'non-chiral', otherwise output 'chiral'.

5.9 Results for non-collision events with p = q = 0

The test procedure is as mentioned above and the results follow what is expected from the logic statement in equation (27). They follow figure 3.

5.10 Construction of non-chiral states and precision of algorithms

Non-chiral states are extremely rare to occur just by the random generation of events and hence to test the logic statements with non-chiral input we constructed them by hand. For example, in the case of collision events when all particle momenta lie in a given plane (that contains the z-axis) the state is manifestly non-chiral. From the latter we can rotate the whole state with the rotor e_1e_2 and still have a non-chiral state. Since the real number 0 can be computationally stored exactly, if we start all our vectors having for example a 0 y-component, then we know the state is non-chiral and can be stored exactly as non-chiral. We can generate similar states by rotation. Of course

⁹In this algorithm b_{12} is the original b vector projected in the 1-2 plane and $b_{rot,12}$ is the b vector extracted from S_2 and projected into the 1-2 plane.

these latter states cannot be computationally stored exactly as non-chiral due to finite precision, but we call them non-chiral up to that precision.

Events which are non-chiral but require a permutation to be mapped back to their original state after parity were also constructed by hand. Indeed, this is a drawback of the testing done on the logic statements, since we followed the structure of the logic statements themselves to find what makes a state non-chiral. In a way the construction of non-chiral states is circular. Concretely, the previous paragraph's idea for collision events emanates from case 1 in section 4.1. The reason it is a drawback is because while calculating expressions such as that in section 4.1 - that belong to the logic statement - we might have omitted a case of non-chirality. However, since we are also generating states randomly in our testing, nothing stops the latter from being non-chiral of any type and the algorithm - which covers all possibilities - will flag up any non-chiral/chiral states that evaluate to false/true on the logic statements derived in this paper - given the calculations of logic statements contain any errors. Of course we expect the randomly generated states to be chiral since it would be very unlikely to randomly generate a non-chiral one.

At various points in this work some algorithms that test chirality would label correctly a state non-chiral but that state would evaluate to false on the logic statement. This is due to the fact that we are doing comparisons of reals - indeed in the logic statements there is a substantial amount of such comparisons. In Python for example, 0.1 + 0.2 == 0.3 gives false. To overcome this issue we have used the 'approx' function from the 'pytest' library [7], which uses a tolerance of 10^{-6} on equality comparison. A simple demonstration from real data follows.

Consider a and b from a collision event with $m_a = m_b = 3$. Here \vec{a} has been generated randomly and \vec{b} was obtained by rotating \vec{a} , hence we expect $a^2 == b^2$ to give true. Note that $a^2 == a \cdot a = dot(a, a)$ where dot is a custom function that performs the Minkowski dot product in Python.

	-2.0142326406285003		-3.4702690814617765
$\vec{a} =$	6.306119476657235	$\vec{b} =$	10.864649396714714
	-9.67682972129608		2.7169717385566954

a^2	b^2	$a^2 == b^2$	$a^2 == \operatorname{approx}(b^2)$	Absolute Error
8.999999999980702	8.9999999999807 <mark>62</mark>	False	True	$1.7763568394002 \cdot 10^{-14}$

The absolute error is defined as $|a^2 - b^2|$ and emanates from rounding error while using finite arithmetic and from quantisation error due to the inexact computer representation of reals. This demonstration quantifies the magnitude of errors in our computational tests.

6 Geometric perspective

Following from the discussion in section 1.7 of [3], let H be the Lorentz group and G be a group such that $G/H \cong \mathbb{Z}/2$ - i.e. G contains an element that acts as parity. Let M be a 24-dimensional

manifold¹⁰ which represents the space of $2 \rightarrow 4$ events. The dimensionality comes from 6 masses and 6 3-momenta. For simplicity consider the compactification¹¹ of M into only collision events with certain energy ranges. By gathering data of such events from hadron colliders we statistically build a path that nature traverses on M.

We now look at the orbit space¹² $\mathcal{O} = M/H$. The latter contains two types of orbits, chiral and non-chiral. Let p be the non-trivial element of $\mathbb{Z}/2 \in G$. The chiral orbits are such that p acting on the orbit takes us off the orbit and into the other chiral orbit. We have two types of chiral orbits which we will call left and right handed. In \mathcal{O} the stabiliser set¹³ for chiral orbits thus consists only of the identity element. For non-chiral states, the stabiliser set is $\mathbb{Z}/2$ i.e. the orbit is fixed under both elements of $\mathbb{Z}/2$.

Now that we have labelled our orbit space we can visualize the path nature traverses on \mathcal{O} shown in figure 4. In order to know where each event in our samples lands on \mathcal{O} , we need to have a function that will distinguish chiral from non-chiral events - this is done with the logic statements derived above - and a function that will distinguish left-handed chiral from right-handed chiral. The latter set of functions are the parity odd event variables derived for example for $2 \rightarrow 3$ processes in [3].



(a) Most samples in the data lie in the left-handed orbit of chiral orbits which indicates parity violation.

(b) Most samples from the data lie in the right-handed orbit of chiral orbits which indicates parity violation.

(c) Even distribution of the two different types of handedness of chiral orbits which does not indicate any parity violation.

Figure 4: Examples of hypothetical data on the orbifold \mathcal{O} and their interpretation.

¹⁰An N dimensional manifold is a set equipped with a topology (which forms then a topological space) that can be locally mapped to \mathbb{R}^N . Locally implies over an open subset (no endpoints included) of M. A topology T on Mis a set of subsets of M. The subsets must satisfy the following axioms: 1) M and the empty set are in T, 2) the intersection of any subsets in T is also in T, and 3) the union of any pair of subsets is also in T.

¹¹Restricting the set which forms the manifold to a compact set. A compact set is defined as closed (contains its endpoints) and bounded (finite cardinality).

¹²This is pronounced M modulo H and forms the set of equivalence classes such that in each class every element can be reached by the repeated application of a given $h \in H$.

¹³The stabiliser set for $\mathcal{O} = M/H$ is the subset of H that leaves an element of \mathcal{O} fixed.

7 Conclusion

In conclusion, we have looked at four different types of $2 \rightarrow 4$ events, namely collision events, non-collisions events with the two initial state particles being represented by massive, massless and zero 4-momenta. For each one of these types, we have calculated the logic statement which is true when evaluated on non-chiral events.

Further, the validity of these results was scrutinised using algorithms that utilize Geometric Algebra to label the chirality of randomly generated events. We have discussed the feasibility of generalising the results to N outgoing particles, with some cases requiring an explicit calculation to do so, while others were more straightforward to generalise.

The results presented in this paper can be used to generate parity-odd Lorentz invariant event variables that possess permutation symmetries between identical particles in the initial and final states, as demonstrated in [3]. These event variables can hint on non-standard parity violating processes through asymmetries in their distribution on hadron collider data.

8 Acknowledgements

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A From events to event variables

Here we present a diagram describing in steps the method we use, going from a set of events to building the event variables. The blue part of the diagram is what we have presented in this paper and the red part is what remains for future work.



Figure 5: A flow chart of the method to go from events to event variables. The blue part is presented in this paper and the red part remains for future work.

B Proofs for algorithms

In this section we present proofs that the algorithms in section 5 cover all possible inputs, i.e. they can label correctly any state their given either 'chiral' or 'non-chiral'. The proofs work with

3-momenta, as do the algorithms, since we have chosen our coordinate system and frame so as to avoid having boosts in our symmetry group.

B.1 Covering of algorithm for collision events

For this type of events, we have p, q aligned with the z-axis in the (p+q) rest frame. Our symmetry actions exclude boosts.

Claim: The algorithm in section 5.2 with its generalisation found in code form in appendix E cover all possible collision event inputs to correctly label them chiral or non-chiral.

Proof: For collision events with permutations we split the proof into two cases of 1_{S_2} or (pq).

For the case of 1_{S_2} , we map p and q back with $R_1 = e_1e_3$. Now the available subspace for rotations is the 1-2 plane. We map the (1-2)-projection of a, namely a_{12} , to its original or for any final state particle x that can be permuted with a, we map the x_{12} to the original a_{12} and perform the permutation (ax). The only degrees of freedom left are permutations between the final state particles excluding a, if any are available. If a is collinear with the 3-axis or a is zero, we repeat the above with b instead of a. If the latter is true for b, we repeat the above with c and if c is also collinear with the 3-axis or zero, we output 'non-chiral' and terminate. Checking for non-chirality with all the aforementioned actions achieves exhaustion for the case of 1_{S_2} .

For the case when we have (pq) available, we can try the above or we can repeat the above but omit R_1 and instead perform (pq). Whenever we check for non-chirality, we can also perform a π rotation in the plane that contains the 3-axis and has normal a_{12} (or any other final state particle we matched to its original in the 1-2 plane), but then we also perform the (pq) swap. The same caveat of a being collinear with the 3-axis or being zero applies here as well. Exhausting degrees of freedom - actions of the symmetry group that leave already matched momenta fixed - ensures covering of the algorithm for any possible input.

B.2 Covering of algorithm for non-collision events with at least one of p and q being massive

For this type of cases we have p and q being stationary, so we are concerned with mapping the final state particles back to their original state with general rotations.

Claim: The algorithm in section 5.4 with its generalisation found in code form in appendix E cover all possible non-collision event inputs (with at least one massive initial particle) to correctly label them chiral or non-chiral.

Proof: For every particle x that can be permuted with a, including a itself, we map x to a and perform (ax). Now that a is fixed, we can only rotate in the plane perpendicular a and do permutations between $\{b, c, d\}$. In what follows we are working in the plane perpendicular to a and w.l.o.g. assume that b has components in that plane. For every particle $y \in \{b, c, d\}$ that can be permuted with b, we map y to b and perform (by). If b is collinear to a, we repeat the latter

with c instead of b, otherwise output 'non-chiral' (since 3 out of 4 are collinear). The only degree of freedom left is (cd), which we also check. We have now exhausted all degrees of freedom and therefore covered all possible inputs.

B.3 Covering of algorithm for non-collision events with both p and q being massless

For theses cases our symmetry group excludes boosts, (pq) swaps and any rotation other than about the z-axis.

Claim: The algorithm in section 5.6 and its generalisation found in code form in appendix E cover all possible non-collision event inputs (with both p and q being massless) to correctly label them chiral or non-chiral.

Proof: Our initial degrees of freedom are rotations about the z-axis and permutations between $\{a, b, c, d\}$. W.l.o.g. we assume that a has permutations and components in the 1-2 plane. Further, all that follows is in the 1-2 plane where rotations are initially allowed. For every particle x that can be permuted with a - including a itself -, we map x to a and perform (ax). Now, the only degrees of freedom are permutations between $\{b, c, d\}$, which we also check. At this point exhaustion of possible actions has been achieved.

B.4 Covering of algorithm for non-collision events with p = q = 0

Claim: The algorithm in section 5.8 and its generalisation found in code form in appendix E cover all possible non-collision event inputs (with p = q = 0) to correctly label them chiral or non-chiral.

Proof: We orient a back to its original state so that the only degrees of freedom are rotations in the subspace perpendicular to a, namely the 1-2 plane, and permutations between $\{b, c, d\}$ if any. In what follows, we are working with vectors projected into the 1-2 plane, leaving the z-component fixed. W.l.o.g we assume that b has permutations and components in the 1-2 plane. For every particle x that can be permuted with b - including b itself -, we map x to b and perform (bx), while also checking for (cd). There are no other degrees of freedom left and thus we have achieved exhaustion.

C Notation

Following the notation and conventions found in the appendices of [3], we present here the meaning of some notation frequently used in this paper. The G stands for Gram determinant.

$$\mathbf{G}\begin{pmatrix}a,b\\c,d\end{pmatrix} \equiv \begin{vmatrix}a\cdot c & a\cdot d\\b\cdot c & b\cdot d\end{vmatrix} = (a\cdot c)(b\cdot d) - (b\cdot c)(a\cdot d)$$

$$\Delta_2(a,b) \equiv G\begin{pmatrix}a,b\\a,b\end{pmatrix}$$
$$\Delta_3(a,b,c) \equiv G\begin{pmatrix}a,b,c\\a,b,c\end{pmatrix} = \begin{vmatrix}a \cdot a & a \cdot b & a \cdot c\\b \cdot a & b \cdot b & b \cdot c\\c \cdot a & c \cdot b & c \cdot c\end{vmatrix}$$

D Case 2 calculation for collision events

This case has $h = 1_{S_2} \cdot (ab)$ and we will go through the explicit calculation of equation (4).

Using

$$\begin{pmatrix} \theta \\ \ddots \\ xy \end{pmatrix} \cdot h \cdot \hat{e} = \begin{pmatrix} \pi \\ \ddots \\ yz \end{pmatrix} \cdot \mathscr{P} \cdot \hat{e}$$
(36)

we start from

$$[(m_a = m_b) \land (a_z = b_z) \land (|\mathbf{a}| = |\mathbf{b}|)] \land \tag{37}$$

$$[(|\mathbf{a}| = |\mathbf{b}| = 0) \lor ((\theta + \beta = \pi + 2\pi n_a - \alpha) \land (\theta + \alpha = \pi + 2\pi n_b - \beta))]\land$$
(38)

$$[(|\mathbf{c}|=0) \lor (\theta + \gamma = \pi + 2\pi n_c - \gamma)] \land$$
(39)

$$\left[\left(|\mathbf{d}| = 0 \right) \lor \left(\theta + \delta = \pi + 2\pi n_d - \delta \right) \right] \tag{40}$$

We now call N the whole bracket of line (37). We also name A_1 the first term in the bracket of line (38) and A_2 the second term in that bracket, namely $A_2 = (\theta + \beta = \pi + 2\pi n_a - \alpha) \wedge (\theta + \alpha = \pi + 2\pi n_b - \beta)$. The same for the rest of the lines using B and C.

Now we have 8 subcases which correspond to choosing one of the two terms in each of the lines (38) to (40). The table below enumerates these subcases.

1)	$A_1B_1C_1$	5)	$A_2B_1C_1$
2)	$A_1B_2C_1$	6)	$A_2B_2C_1$
3)	$A_1B_1C_2$	7)	$A_2B_1C_2$
4)	$A_1B_2C_2$	8)	$A_2B_2C_2$

D.1 Subcase 1: $A_1B_1C_1$

This subcase has $|\mathbf{a}| = |\mathbf{b}| = |\mathbf{c}| = |\mathbf{d}| = 0 \Rightarrow$ all 3-vectors of the final state live on the z-axis which is already covered by case 1 and can thus be discarded.

D.2 Subcases 2-4

These subcases are also covered by case 1 and can be discarded. In each one of them we find that all final state 3-vectors lie in the same plane.

D.3 Subcase 5: $A_2B_1C_1$

Remember N refers to line (37). Subcase 5 has $N \wedge (\theta + \beta = \pi + 2\pi n_a - \alpha) \wedge (\theta + \alpha = \pi + 2\pi n_b - \beta) \wedge (|\mathbf{c}| = 0) \wedge (|\mathbf{d}| = 0)$. The two brackets containing angles give that $\alpha + \beta = \pi - \theta + \pi (n_a + n_b)$. However, we can always find a θ in the symmetry group to satisfy the condition and hence effectively α and β are unconstrained, but we must $(|\mathbf{a}| \neq 0) \wedge (|\mathbf{b}| \neq 0)$. A general event of this subcase can be described by $N \wedge (|\mathbf{a}| \neq 0) \wedge (|\mathbf{b}| \neq 0) \wedge (|\mathbf{c}| = 0) \wedge (|\mathbf{d}| = 0)$. Note that for example $|\mathbf{a}| \neq 0$ can be written in a Lorentz invariant form using $\Delta_3(a, p, q) \neq 0$, which follows from Lemma 3.34 of [3].

D.4 Subcase 6: $A_2B_2C_1$

We start with $N \wedge (\theta + \beta = \pi + 2\pi n_a - \alpha) \wedge (\theta + \alpha = \pi + 2\pi n_b - \beta) \wedge (\gamma = \frac{1}{2}(\pi - \theta) + 2\pi n_c) \wedge (|\mathbf{d}| = 0)$. The bracket with the angle γ has just been algebraicly rearranged from line (39) - remember the Greek letter angles refer to angles in the transverse plane perpendicular to the z-axis. Now, the brackets with angles involved give the following with a possible solution for the angles α, β, γ shown on the right hand side

$$\begin{aligned} \alpha + \beta &= \pi + 2\pi n_a - \theta & \alpha &= \pi - \theta + 2\pi n_a \\ \alpha + \beta &= \pi + 2\pi n_b - \theta & \beta &= 0 \\ \gamma &= \frac{1}{2}(\pi - \theta) + 2\pi n_c & \gamma &= \frac{1}{2}(\pi - \theta) + 2\pi n_c \end{aligned}$$

W.l.o.g. setting α and γ anywhere in the transverse plane, β is forced to be the reflection of α in the line defined by γ - see figure 6. Hence we choose $G\begin{pmatrix}a-b,p+q\\c&,p+q\end{pmatrix} = 0$ to describe this. To see the latter we expand the Gram determinant which gives $0 = (a-b) \cdot c = (m_a - m_b)m_c - (\vec{a} - \vec{b}) \cdot \vec{c} = -(\vec{a} - \vec{b}) \cdot \vec{c} = -(\vec{a} - \vec{b}) \cdot \vec{c} = 0$. The last equality follows from the condition $a_z = b_z$ and we also use the condition $m_a = m_b$.



Figure 6: An example of \mathbf{a} and \mathbf{b} being reflections of each other in the ray defined by \mathbf{c} . The figure was constructed using [8].

D.5 Subcase 7: $A_2B_1C_2$

This subcase follows subcase 6 by swapping c with d.

D.6 Subcase 8: $A_2B_2C_2$

This subcase has $N \wedge (\theta + \beta = \pi + 2\pi n_a - \alpha) \wedge (\theta + \alpha = \pi + 2\pi n_b - \beta) \wedge (\theta + \gamma = \pi + 2\pi n_c - \gamma) \wedge (\theta + \delta = \pi + 2\pi n_d - \delta)$. We can see immediately that the brackets other than N give

$$n_a = n_b$$

$$\gamma - \delta = 2\pi (n_c - n_d) = 0 \mod 2\pi$$

$$\gamma - \frac{1}{2} (\alpha + \beta) = \pi (n_a - n_c)$$

$$\delta - \frac{1}{2} (\alpha + \beta) = \pi (n_a - n_d)$$

$$\Rightarrow \gamma = \delta \mod \pi$$

This is telling us that **c** and **d** form a ray in the transverse plane in which **a** and **b** are reflections of each other. We can describe this in a Lorentz invariant form as $\left(\left(G\begin{pmatrix}a-b,p+q\\c&,p+q\end{pmatrix}=0\right)\land\left(G\begin{pmatrix}a-b,p+q\\d&,p+q\end{pmatrix}=0\right)\right)\Rightarrow G\begin{pmatrix}a-b,p+q\\c-d,p+q\end{pmatrix}=0.$

D.7 Final result

Gathering all the results from these subcases, we combine them to form the result presented in equation (4).

E Code

Below we present the full code for all types of events considered. The titles of the files correspond to the initial state particles and the code can also be found in [9].

Listings

collision_events_algorithm.py	29
non_collision_one_massive_algorithm.py	45
non_collision_massless_algorithm.py	50
non_collision_zeros_algorithm.py	55

Code file: collision_events_algorithm.py

```
import time
from numpy import pi, cos, sin, e, tan, arctan
from clifford.g3 import blades
import matplotlib.pyplot as plt
from mpl_tcolkits.mplot3d import Axes3D
import numpy as np
from random import uniform, seed, randint
from sympy import LeviCivita as eps
0
# fig = plt.figure()
# ax = fig.add_subplot(111, projection='3d')
```

```
12
13 e1, e2, e3 = blades['e1'], blades['e2'], blades['e3']
14 I = e1*e2*e3 # Pseudoscalar of 3D Euclidean geometric algebra
15
16 def plot_state(ax, p, q, a, b, c, d):
17
          X = (0)
18
           Y = (0)
19
          Z = (0)
20
21
           p1, p2, p3 = p[0], p[1], p[2]
          p_1, p_2, p_3 = p_1(0), p_1(1), p_2(1)

q_1, q_2, q_3 = q_1(0), q_1(1), q_1(2)

a_1, a_2, a_3 = a_1(0), a_1(1), a_1(2)
23
^{24}
          b1, b2, b3 = b[0], b[1], b[2]
25
          c1, c2, c3 = c[0], c[1], c[2]
26
          d1, d2, d3 = d[0], d[1], d[2]
27
28
           ax.quiver(X, Y, Z, p1, p2, p3, color='r', linestyle='-', label='p')
29
          ax.quiver(X, Y, Z, q1, q2, q3, color='r', linestyle='-', label='p')
ax.quiver(X, Y, Z, q1, q2, q3, color='k', linestyle='-', label='q')
ax.quiver(X, Y, Z, a1, a2, a3, color='b', linestyle='-', label='a')
ax.quiver(X, Y, Z, b1, b2, b3, color='g', linestyle='-', label='b')
ax.quiver(X, Y, Z, c1, c2, c3, color='y', linestyle='-', label='c')
ax.quiver(X, Y, Z, d1, d2, d3, color='a', linestyle='-', label='c')
30
31
32
33
           ax.quiver(X, Y, Z, d1, d2, d3, color='orange', linestyle='-', label='d')
34
35
           ax.set_xlabel('x')
           ax.set_ylabel('y')
36
           ax.set_zlabel('z')
37
38
           ax.set_xticks([])
39
           ax.set_yticks([])
40
           ax.set_zticks([])
41
          limit = 10
42
           ax.set_xlim([-limit, limit])
          ax.set_ylim([-limit, limit])
ax.set_zlim([-limit, limit])
43
44
45
           ax.view_init(elev=1, azim=pi / 2)
46
          plt.legend()
47
48 def plot_parity_state(ax, p, q, a, b, c, d):
49
50
          X = (0)
          Y = (0)
Z = (0)
51
52
53
          p1, p2, p3 = -p[0], -p[1], -p[2]
q1, q2, q3 = -q[0], -q[1], -q[2]
a1, a2, a3 = -a[0], -a[1], -a[2]
54
56
           b1, b2, b3 = -b[0], -b[1], -b[2]
57
          c1, c2, c3 = -c[0], -c[1], -c[2]
d1, d2, d3 = -d[0], -d[1], -d[2]
58
59
60
           ax.quiver(X, Y, Z, p1, p2, p3, color='r', linestyle='--', label='p')
61
          ax.quiver(X, Y, Z, q1, q2, q3, color='k', linestyle='--', label='q')
ax.quiver(X, Y, Z, a1, a2, a3, color='b', linestyle='--', label='q')
ax.quiver(X, Y, Z, a1, a2, a3, color='b', linestyle='--', label='a')
ax.quiver(X, Y, Z, b1, b2, b3, color='g', linestyle='--', label='b')
ax.quiver(X, Y, Z, c1, c2, c3, color='y', linestyle='--', label='c')
62
63
64
65
           ax.quiver(X, Y, Z, d1, d2, d3, color='orange', linestyle='--', label='d')
66
           ax.set_xlabel('x')
67
           ax.set_ylabel('y')
68
           ax.set_zlabel('z')
69
70
           ax.set_xticks([])
71
           ax.set_yticks([])
72
           ax.set_zticks([])
           limit = 10
73
           ax.set_xlim([-limit, limit])
74
           ax.set_ylim([-limit, limit])
75
          ax.set_zlim([-limit, limit])
ax.view_init(elev=1, azim=pi / 2)
76
77
           plt.legend()
78
          plt.show()
79
80
```

```
81 # -----
82
83 # For a collision event:
84
85 def parity(S):
       return [-v for v in S]
86
87
88 def rotate(S, R):
       return [R*v*~R for v in S]
89
90
91 def multivec_to_vec(a):
       return np.array([a[1], a[2], a[3]])
92
93
94 def energy(m,p):
       p = multivec_to_vec(p)
95
       return np.sqrt(m**2 + np.linalg.norm(p)**2)
96
97
98 def epsilon(a, b, c, d):
99
       summation = 0
100
       for i in range(0, 4):
102
            for j in range(0, 4):
    for k in range(0, 4):
        for l in range(0, 4):
103
104
105
                        summation += eps(i, j, k, l) * a[i] * b[j] * c[k] * d[l]
106
107
108
       return summation
109
110 def dot(a, b):
111
112
        # Minkowski metric
113
114
       return a[0]*b[0] - a[1]*b[1] - a[2]*b[2] - a[3]*b[3]
115
116 def Gram_det_2(a,b,c,d):
117
118
       # a b
119
       # c d
120
121
       return (dot(a, c))*(dot(b, d)) - (dot(a, d))*(dot(b, c))
122
123 def sym_2_Gram_det(a,b):
124
       return Gram_det_2(a,b,a,b)
125
126 def sym_3_Gram_det(a,b,c):
127
       M = [[dot(a,a),dot(a,b),dot(a,c)],[dot(b,a),dot(b,b),dot(b,c)],[dot(c,a),dot(c,b),dot(c,c)]]
        return np.linalg.det(M)
128
129
130 def swap(S,idx_1,idx_2):
131
132
        tmp = S[idx_1]
        S[idx_1] = S[idx_2]
133
       S[idx_2] = tmp
134
135
136
        return S
137
138 def permute_with_idx(M, E, idx_to_permute):
139
       same_mass_with_idx = [idx for idx in range(len(M)) if M[idx] == M[idx_to_permute] and idx !=
idx_to_permute and idx != 0 and idx != 1]
140
        same_energy_with_idx = [idx for idx in range(len(E)) if E[idx] == E[idx_to_permute] and idx
141
        != idx_to_permute]
142
        return list(set(same_mass_with_idx) and set(same_energy_with_idx))
143
144
145 def permutation_boolean(M, E, idx_1, idx_2):
146
147 if (M[idx_1] == M[idx_2]) and (E[idx_1] == E[idx_2]):
```

```
148
                        return True
149
                 else:
150
                        return False
151
152 def logic_statement_true_for_non_chiral(S, E):
153
                p = multivec_to_vec(S[0])
154
                p = np.insert(p, 0, E[0])
                q = multivec_to_vec(S[1])
156
                q = np.insert(q, 0, E[1])
157
                a = multivec_to_vec(S[2])
158
                a = np.insert(a, 0, E[2])
159
                b = multivec_to_vec(S[3])
                b = np.insert(b, 0, E[3])
161
                c = multivec_to_vec(S[4])
162
                c = np.insert(c, 0, E[4])
163
                d = multivec_to_vec(S[5])
164
                d = np.insert(d, 0, E[5])
                RF = p + q
166
167
                case_1 = ((epsilon(a,b,p,q) == 0) and (epsilon(a,c,p,q) == 0) and (epsilon(a,d,p,q) == 0)
168
                 and (epsilon(b,d,p,q) == 0)
                                   and (epsilon(b,c,p,q) == 0) and (epsilon(c,d,p,q) == 0))
169
171
                case 2 =
                                    ((dot(a,a) == dot(b,b)) and (Gram_det_2(a-b,RF,p-q,RF) == 0) and (Gram_det_2(a-b,RF,p-q,RF) == 0)
                 RF, a+b, RF) == 0)
                                     and (((sym_3_Gram_det(a, p, q) == 0) and (sym_3_Gram_det(b, p, q) == 0) and (
                 sym_3_Gram_det(c,p,q) = 0 and (sym_3_Gram_det(d,p,q) = 0)
                                        or ((sym_3_Gram_det(a,p,q) != 0) and (sym_3_Gram_det(b,p,q) != 0) and (
173
                 sym_3_Gram_det(c,p,q) != 0) and (sym_3_Gram_det(d,p,q) == 0) and (Gram_det_2(a-b,RF,c,RF)
                 == 0))
174
                                        or ((sym_3_Gram_det(a,p,q) != 0) and (sym_3_Gram_det(b,p,q) != 0) and (
                 sym_3_Gram_det(d,p,q) != 0) and (sym_3_Gram_det(c,p,q) == 0) and (Gram_det_2(a-b,RF,d,RF)
                 == 0))
                                        or ((sym_3_Gram_det(a,p,q) !=0) and (sym_3_Gram_det(b,p,q) != 0) and (
                 sym_3_Gram_det(d,p,q) != 0) and (sym_3_Gram_det(c,p,q) != 0) and (Gram_det_2(a-b,RF,c,RF)
                 == 0) and (Gram_det_2(a-b,RF,d,RF) == 0))))
176
177
                 def case_2_symmetry(p, q, a, b, c, d):
 178
179
                        return ((dot(a,a) == dot(b,b)) and (Gram_det_2(a-b,RF,p-q,RF) == 0) and (Gram_det_2(a-b,
                 RF, a+b, RF) == 0
180
                                     and (((sym_3_Gram_det(a,p,q) == 0) and (sym_3_Gram_det(b,p,q) == 0) and (
                 sym_3_Gram_det(c, p, q) = 0 and (sym_3_Gram_det(d, p, q) = 0)
                                        or ((sym_3_Gram_det(a,p,q) != 0) and (sym_3_Gram_det(b,p,q) != 0) and (
181
                 sym_3_Gram_det(c,p,q) != 0) and (sym_3_Gram_det(d,p,q) == 0) and (Gram_det_2(a-b,RF,c,RF)
                 == 0))
                                        or ((sym_3_Gram_det(a,p,q) != 0) and (sym_3_Gram_det(b,p,q) != 0) and (
182
                 sym_3_Gram_det(d,p,q) != 0) and (sym_3_Gram_det(c,p,q) == 0) and (Gram_det_2(a-b,RF,d,RF)
                 == 0))
                                        or ((sym_3_Gram_det(a,p,q) != 0) and (sym_3_Gram_det(b,p,q) != 0) and (
183
                 sym_3_Gram_det(d,p,q) != 0) and (sym_3_Gram_det(c,p,q) != 0) and (Gram_det_2(a-b,RF,c,RF)
                 == 0) and (Gram_det_2(a-b,RF,d,RF) == 0))))
184
185
                case_3 = case_2_symmetry(p, q, c, d, a, b) # h = (cd)
                case_4 = case_2_symmetry(p, q, b, c, a, d) # h = (bc)
186
                case_5 = case_2_symmetry(p, q, b, d, a, c)
187
                                                                                                              # h = (bd)
                case_6 = case_2_symmetry(p, q, a, c, b, d) # h = (ac)
188
189
                case_7 = case_2_symmetry(p, q, a, d, c, b) # h = (ad)
190
191
                # TODO: In case 16 green and blue bracket are the negation of each other so I can evaluate
                 once for efficiency
192
                \texttt{case_16} = ((\texttt{dot}(\texttt{a},\texttt{a}) \texttt{==} \texttt{dot}(\texttt{b},\texttt{b})) \texttt{ and } (\texttt{dot}(\texttt{c},\texttt{c}) \texttt{==} \texttt{dot}(\texttt{d},\texttt{d})) \texttt{ and } (\texttt{Gram\_det}_2(\texttt{a-b},\texttt{RF},\texttt{p-q},\texttt{RF})) \texttt{ and } (\texttt{and}(\texttt{and})) \texttt{ and } (\texttt{and}) \texttt
193
                 == 0) and (Gram_det_2(a-b, RF, a+b, RF) == 0) and (Gram_det_2(c-d, RF, p-q, RF) == 0) and (
                 Gram_det_2(c-d, RF, c+d, RF) == 0)
                 and (((sym_3_Gram_det(a,p,q)==0) and (sym_3_Gram_det(b,p,q)==0) and (sym_3_Gram_det(c,p,q)!=0) and (sym_3_Gram_det(d,p,q)!=0) or (sym_3_Gram_det(c,p,q)==0) and
194
                 (sym_3\_Gram\_det(d,p,q)==0) and (sym_3\_Gram\_det(a,p,q)!=0) and (sym_3\_Gram\_det(b,p,q)!=0))
```

```
195
                                                           or ((Gram_det_2(a-b,RF,c+d,RF)==0) or (Gram_det_2(c-d,RF,b,RF)==0) or (
                     Gram_det_2(a-b, RF, d, RF) == 0)))))
196
197
                    def case_16_symmetry(p,q,a,b,c,d):
198
                              return ((dot(a,a) == dot(b,b)) and (dot(c,c) == dot(d,d)) and (Gram_det_2(a-b,RF,p-q,RF))
199
                        == 0) and (Gram_det_2(a-b,RF,a+b,RF) == 0) and (Gram_det_2(c-d,RF,p-q,RF) == 0) and (
                     Gram_det_2(c-d, RF, c+d, RF) == 0)
                                              and (((sym_3_Gram_det(a,p,q)==0) and (sym_3_Gram_det(b,p,q)==0) and (
200
                     sym_3_Gram_det(c, p, q) = 0 and (sym_3_Gram_det(d, p, q) = 0) or (sym_3_Gram_det(c, p, q) = 0) and
                     (sym_3_Gram_det(d,p,q)==0) and (sym_3_Gram_det(a,p,q)!=0) and (sym_3_Gram_det(b,p,q)!=0))
                                                           or ((Gram_det_2(a-b,RF,c+d,RF)==0) or (Gram_det_2(c-d,RF,b,RF)==0) or (
201
                     Gram_det_2(a-b, RF, d, RF) == 0))))
202
                    case_17 = case_16_symmetry(p, q, a, c, b, d) # h = (ac)(bd)
203
                    case_18 = case_16_symmetry(p, q, a, d, c, b) # h = (ad)(bc)
204
205
                    case_{19} = ((dot(a,a) == dot(b,b) == dot(c,c) == dot(d,d)) and (Gram_det_2(a-b,RF,a+b,RF) == dot(d,d))
206
                     0) and (Gram_det_2(b-c, RF, b+c, RF) == 0) \setminus
                                               and (Gram_det_2(c-d, RF, c+d, RF) == 0) and (Gram_det_2(a-b, RF, p-q, RF) == 0) and (
207
                     Gram_det_2(b-c, RF, p-q, RF) == 0) \setminus
                                              and (Gram_det_2(c-d, RF, p-q, RF) == 0) and (a == c) and (b == d))
208
209
210
                    def case_19_symmetry(p,q,a,b,c,d):
211
                              return ((dot(a,a) == dot(b,b) == dot(c,c) == dot(d,d)) and (Gram_det_2(a-b,RF,a+b,RF) ==
212
                        0) and (Gram_det_2(b-c, RF, b+c, RF) == 0) \setminus
                                              and (Gram_det_2(c-d,RF,c+d,RF) == 0) and (Gram_det_2(a-b,RF,p-q,RF) == 0) and (
213
                     Gram_det_2(b-c, RF, p-q, RF) == 0) \setminus
                                             and (Gram_det_2(c-d, RF, p-q, RF) == 0) and (a == c) and (b == d))
214
215
216
                    case_{20} = case_{19}_{symmetry}(p,q,a,b,d,c) # h = (dbac)
                    case_22 = case_19_symmetry(p,q,a,c,d,b) # h = (bcad)
217
218
219
                    case_{25} = ((dot(p,p) == dot(q,q)) and (Gram_det_2(a,RF,p-q,RF) == 0) and (Gram_det_2(b,RF,p-q,RF) == 0)
                    q,RF) == 0) \
                                           and (Gram_det_2(c, RF, p-q, RF) == 0) and (Gram_det_2(d, RF, p-q, RF) == 0))
220
221
                    case_{26} = ((dot(p,p) == dot(q,q)) and (dot(a,a) == dot(b,b)) and (Gram_det_2(a+b,RF,p-q,RF))
222
                     == 0) and (Gram_det_2(a-b, RF, a+b, RF) == 0)
                                                 and (Gram_det_2(c, RF, p-q, RF) == 0) and (Gram_det_2(d, RF, p-q, RF) == 0)
223
                                                 and (sym_3_Gram_det(a,p,q) == 0 or sym_3_Gram_det(a+b,p,q) == 0 or sym_3_Gram_det
224
                     (a-b,p,q) == 0))
225
226
                    def case_26_symmetry(p,q,a,b,c,d):
227
                              return ((dot(p,p) == dot(q,q)) and (dot(a,a) == dot(b,b)) and (Gram_det_2(a+b,RF,p-q,RF))
228
                        == 0) and (Gram_det_2(a-b, RF, a+b, RF) == 0)
                                                 and (Gram_det_2(c, RF, p-q, RF) == 0) and (Gram_det_2(d, RF, p-q, RF) == 0)
229
                                                 and (sym_3_Gram_det(a,p,q) == 0 or sym_3_Gram_det(a+b,p,q) == 0 or sym_3_Gram_det
230
                     (a-b,p,q) == 0))
231
232
                    case_27 = case_26_symmetry(p, q, c, d, a, b) # h = (cd)
                    case_28 = case_26_symmetry(p, q, c, b, a, d) # h = (bc)
233
234
                    case_{29} = case_{26}_{symmetry}(p, q, d, b, c, a) # h = (bd)
                    case_{30} = case_{26}_{symmetry}(p, q, a, c, b, d) # h = (ac)
235
236
                    case_{31} = case_{26}_{symmetry}(p, q, a, d, c, b) # h = (ad)
237
238
                    case_32 = ((dot(p,p) == dot(q,q)) and (dot(b,b) == dot(c,c) == dot(d,d)) and (Gram_det_2(a, case_3)) and (dot(b,b) == dot(c,c) == dot(d,d)) and (dot(b,b) == dot(d,d)) and (dot
239
                     \begin{array}{rcl} RF,p-q,RF) &=& 0 \end{array} \\ & \text{and} & \left( \text{Gram\_det}_2(b,\text{RF},p-q,\text{RF}) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & =& 0 \end{array} \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \right) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \\ & \text{and} & \left( \text{Gram\_det}_2(c,\text{RF},p-q,\text{RF}) \right) \\ & \text{
240
                     Gram_det_2(b-c, RF, b+c, RF) == 0) \setminus
                                              and (Gram_det_2(c-d,RF,c+d,RF) == 0) and (Gram_det_2(a,RF,p-q,RF) == 0) and (
241
                     epsilon((b+d),c,p,q) == 0) \setminus
                                              and (epsilon((b+c),d,p,q) == 0) and (epsilon((c+d),b,p,q) == 0))
242
243
                    def case_32_symmetry(p,q,a,b,c,d):
244
245
```

```
return ((dot(p,p) == dot(q,q)) and (dot(b,b) == dot(c,c) == dot(d,d)) and (Gram_det_2(a, b))
246
             RF, p-q, RF) == 0) and (Gram_det_2(b, RF, p-q, RF) == 0) \setminus
                            and (Gram_det_2(c, RF, p-q, RF) == 0) and (Gram_det_2(d, RF, p-q, RF) == 0) and (
247
             Gram_det_2(b-c, RF, b+c, RF) == 0) \setminus
                             and (Gram_det_2(c-d, RF, c+d, RF) == 0) and (Gram_det_2(a, RF, p-q, RF) == 0) and (
248
             epsilon((b+d),c,p,q) == 0) \setminus
                            and (epsilon((b+c),d,p,q) == 0) and (epsilon((c+d),b,p,q) == 0))
249
250
            case_34 = case_32_symmetry(p, q, d, b, c, a) # h = (cba)
251
            case_{35} = case_{32}_{symmetry}(p, q, c, a, d, b) # h = (dba)
252
            case_37 = case_32_symmetry(p, q, b, a, c, d) # h = (dca)
253
254
            case_40 = ((dot(p,p) == dot(q,q)) and (dot(a,a) == dot(b,b)) and (dot(c,c) == dot(d,d)) and
255
             (Gram_det_2(a+b, RF, p-q, RF) == 0) \setminus
                            and (Gram_det_2(c+d,RF,p-q,RF) == 0) \setminus
256
                             and ((sym_3_Gram_det(a+b,p,q) == 0 or sym_3_Gram_det(a-b,p,q) == 0)
or ((sym_3_Gram_det(c+d,p,q) == 0) or (sym_3_Gram_det(c-d,p,q) == 0))))
257
258
259
260
            def case_40_symmetry(p,q,a,b,c,d):
261
                  return ((dot(p,p) == dot(q,q)) and (dot(a,a) == dot(b,b)) and (dot(c,c) == dot(d,d)) and
262
               (Gram_det_2(a+b, RF, p-q, RF) == 0) \setminus
                            and (Gram_det_2(c+d, RF, p-q, RF) == 0) \setminus
263
                             and ((sym_3_Gram_det(a+b,p,q) == 0 \text{ or } sym_3_Gram_det(a-b,p,q) == 0)
264
265
                                     or ((sym_3_Gram_det(c+d,p,q) == 0) or (sym_3_Gram_det(c-d,p,q) == 0))))
266
267
            case_41 = case_40_symmetry(p, q, a, c, b, d) # h = (ac)(bd)
            case_42 = case_40_symmetry(p, q, a, d, c, b) # h = (ad)(cb)
268
269
            case_43 = ((dot(p,p) == dot(q,q)) and (dot(a,a) == dot(b,b) == dot(c,c) == dot(d,d)) and (dot(a,b) == dot(b,b) == dot(c,c) == dot(c,c) == dot(d,d)) and (dot(a,a) == dot(b,b) == dot(c,c) == dot(d,d)) and (dot(
270
             Gram_det_2(a-b,RF,a+b,RF) == 0)
271
             and (Gram_det_2(b-c,RF,b+c,RF) == 0) and (Gram_det_2(c-d,RF,c+d,RF) == 0) and (Gram_det_2(a+
             b, RF, p-q, RF) == 0) and (Gram_det_2(b+c, RF, p-q, RF) == 0)
272
             and (Gram_det_2(c+d, RF, p-q, RF) == 0) and ((sym_3_Gram_det(a, p, q) == 0)
             or ((epsilon(p+q,a-c,p,b) == 0) and (epsilon(p+q,b-d,a,p) == 0))
273
             or ((sym_3_Gram_det(a-c,p,q) == 0) and (sym_3_Gram_det(b-d,p,q) == 0)
274
                   and ((sym_3_Gram_det(a+b,p,q) == 0) or ((Gram_det_2(a+b,RF,p-q,RF) == 0) and (
275
             sym_3_Gram_det(a-b,p,q) == 0))))))
276
             def case_43_symmetry(p,q,a,b,c,d):
277
278
279
                   return ((dot(p,p) == dot(q,q)) and (dot(a,a) == dot(b,b) == dot(c,c) == dot(d,d)) and (
             Gram_det_2(a-b,RF,a+b,RF) == 0)
             and (Gram_det_2(b-c,RF,b+c,RF) == 0) and (Gram_det_2(c-d,RF,c+d,RF) == 0) and (Gram_det_2(a+
280
             b, RF, p-q, RF) == 0) and (Gram_det_2(b+c, RF, p-q, RF) == 0)
             and (Gram_det_2(c+d,RF,p-q,RF) == 0) and ((sym_3_Gram_det(a,p,q) == 0)
281
            or ((epsilon(p+q,a-c,p,b) == 0) and (epsilon(p+q,b-d,a,p) == 0))
282
            or ((sym_3_Gram_det(a-c,p,q) == 0) and (sym_3_Gram_det(b-d,p,q) == 0)
283
                   and ((sym_3_Gram_det(a+b,p,q) == 0) or ((Gram_det_2(a+b,RF,p-q,RF) == 0) and (
284
             sym_3_Gram_det(a-b,p,q) == 0))))))
285
286
            case_44 = case_43_symmetry(p, q, a, b, d, c) # h = (dbac)
            case_{45} = case_{43} symmetry(p, q, b, a, c, d)
287
                                                                                      # h = (dcab)
            case_46 = case_43_symmetry(p, q, a, c, b, d) # h = (dbca)
288
            case_47 = case_43_symmetry(p, q, c, b, a, d)
289
                                                                                      \# h = (dabc)
            case_48 = case_43_symmetry(p, q, b, c, a, d) # h = (dacb)
290
291
292
            return (case_1 or case_2 or case_3 or case_4 or case_5 or case_6 or case_7 or case_16 or
             case_17 or case_18
                         or case_19 or case_20 or case_22 or case_25 or case_26 or case_27 or case_28 or
293
             case_29 or case_30
                         or case_31 or case_32 or case_34 or case_35 or case_37 or case_40 or case_41 or
294
             case_42 or case_43
                         or case_44 or case_45 or case_46 or case_47 or case_48)
295
296
297 def construct_state():
298
            mp, mq, ma, mb, mc, md = randint(0, 10), randint(0, 10), randint(0, 10), randint(0, 10),
299
             randint(0, 10), randint(0, 10)
```

```
300
        p = uniform(-10, 10) * e3
301
        q = -p
302
303
        a = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
b = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
304
305
        c = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
306
        d = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
307
308
        Ep, Eq, Ea, Eb, Ec, Ed = energy(mp, p), energy(mq, q), energy(ma, a), energy(mb, b), energy(
309
        mc, c), energy(md, d)
310
        M = [mp, mq, ma, mb, mc, md]
311
        E = [Ep, Eq, Ea, Eb, Ec, Ed]
312
        S = [p, q, a, b, c, d]
313
314
        return S. E. M
315
316
317 def construct_non_chiral_state(): # Trick
318
        mp, mq, ma, mb, mc, md = 1, 1, 1, 1, 1, 1
319
320
        p = uniform(-10, 10) * e3
321
        q = -p
322
323
        a = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
324
        b = a[1] * e1 - a[2] * e2 + a[3] * e3
325
        R = e**(uniform(0,2*pi)*e1*e2)
326
327
        c = R*a*^R
        d = c[1] * e1 - c[2] * e2 + c[3] * e3
328
329
        Ep, Eq, Ea, Eb, Ec, Ed = energy(mp, p), energy(mq, q), energy(ma, a), energy(mb, b), energy(mc, c), energy(md, d)
330
331
332
        M = [mp, mq, ma, mb, mc, md]
333
        E = [Ep, Eq, Ea, Eb, Ec, Ed]
334
        S = [p, q, a, b, c, d]
335
336
        return S, E, M
337
338 def chirality_test():
339
340
        chiral_states = []
        non_chiral_states = []
341
342
        S, E, M = construct_non_chiral_state()
343
        a, b, c, d = S[2], S[3], S[4], S[5]
344
345
        # These lists hold indices (as they appear in S) of the particles that can be permuted with
346
        a,b,c and d respectively
347
        permute_with_a = permute_with_idx(M, E, 2)
348
        permute_with_b = permute_with_idx(M, E, 3)
        permute_with_c = permute_with_idx(M, E, 4)
349
        permute_with_d = permute_with_idx(M, E, 5)
350
351
352
        permutation_dictionary = {3: permute_with_b, 4: permute_with_c, 5: permute_with_d}
353
        S_parity = parity(S) # Perform parity on the set of momenta
354
355
356
        flag = False
357
        if not permutation_boolean(M, E, 0, 1): # If we cant permute p (index 0) with q (index 1)
358
359
            if (a[1] == 0 \text{ and } a[2] == 0) or (a == 0):
360
361
                if (b[1] == 0 and b[2] == 0) or (b == 0):
362
363
                     if (c[1] == 0 and c[2] == 0) or (c == 0):
364
365
```

```
flag = True
366
367
368
                     else: # Here we consider that a,b are either e3 collinear or 0, only c and d are
          in the 1-2 plane
369
                         # We can map c_{12} to its original or d_{12} to the original c_{12} and swap (cd)
370
          if they can be
                         # permuted.
371
372
                          # Since a and b are fixed by R1 = e1e3 we only want to consider permutations
373
          (cd)
                          # Remember that idx 2 corresponds to a and idx 3 corresponds to b in S
374
                         permute_with_c_new = list([idx for idx in permute_with_c if (idx != 2) and (
375
         idx != 3)])
376
                          R1 = e1 * e3
377
378
                          S1 = rotate(S_parity, R1)
379
380
                          for idx in permute_with_c_new+[4]: # The index of c is 4 in the list S
381
382
                              # Map x_12_rotated to c_12_original
383
384
                              x = S1[idx]
385
                              x_{12} = x - x[3] * e3
c_{12} = c - c[3] * e3
386
387
                              n = (x_{12} + c_{12}).normal()
388
                              if n = 0: # If x_12 and c_12 are anti-parallel then we need a pi
389
         rotation
                                  R2 = e1 * e2
390
391
                              else: # Otherwise we construct the rotor as usual with the form R = (
         final destination)*n
                                  R2 = c_{12.normal()*n}
392
                              S2 = rotate(S1, R2)
393
                              S3 = swap(S2, idx, 4)
394
395
                              if S == S3:
396
397
                                  flag = True
398
399
                 else: # Here we consider that a is collinear with e3 or is 0 but b is not
400
401
                     # We map x_{12} to b_{12} original and consider permutations between (cd), where
         x_{12} can be (b,c,d)_{12}
402
403
                     permute_with_b_new = list([idx for idx in permute_with_b if (idx != 2)])
404
                     R1 = e1 * e3
405
406
                     S1 = rotate(S_parity, R1)
407
408
409
                     for idx in permute_with_b_new + [3]: # The index of b is 3 in the list S
410
                         # Map x_12_rotated to b_12_original
411
412
413
                         x = S1[idx]
                         x_12 = x - x[3] * e3

b_12 = b - b[3] * e3
414
415
                         n = (x_112 + b_112).normal()
if n == 0: # If x_12 and b_12 are anti-parallel then we need a pi rotation
416
417
                             R2 = e1 * e2
418
                          else: # Otherwise we construct the rotor as usual with the form R = (final
419
         destination)*n
                             R2 = b_{12.normal()} * n
420
                          S2 = rotate(S1, R2)
421
                          S3 = swap(S2, idx, 3)
422
423
                          if S == S3:
424
                              flag = True
425
426
```

```
if permutation_boolean(M, E, 4, 5): # If (cd) is possible
427
428
429
                                                       S4 = swap(S3, 4, 5)
430
                                                      if S == S4:
431
432
                                                              flag = True
433
434
                      else: # Here we consider that a is not collinear with e3 and not 0
435
436
                               # We need to map x_{12} to a_{12} original and consider permutations (bcd)
437
438
                              R1 = e1 * e3
439
440
                              S1 = rotate(S_parity, R1)
441
442
                              for idx in permute_with_a + [2]: # The index of a is 2 in the list S
443
444
                                       # Map x_12_rotated to a_12_original
445
446
                                      x = S1[idx]
447
                                      x_{12} = x - x[3] * e3
a_{12} = a - a[3] * e3
448
449
                                      a_{12} = a_{12}, a_{13}, a_{13
450
451
                                             R2 = e1 * e2
452
                                       else: # Otherwise we construct the rotor as usual with the form R = (final
453
                destination)*n
                                             R2 = a_{12.normal()} * n
454
                                       S2 = rotate(S1, R2)
455
                                      S3 = swap(S2, idx, 2)
456
457
                                       if S == S3:
458
                                              flag = True
459
460
                                      flag_tmp_1 = permutation_boolean(M, E, 3, 4) # This checks if (bc) is available
461
462
463
                                       if flag_tmp_1:
464
                                              S4 = swap(S3, 3, 4)
                                               if S == S4:
465
466
                                                      flag = True
467
468
                                       flag_tmp_2 = permutation_boolean(M, E, 3, 5) # This checks if (bd) is available
469
                                       if flag_tmp_2:
470
471
                                              S5 = swap(S3, 3, 5)
472
                                               if S == S5:
                                                      flag = True
473
474
475
                                       if flag_tmp_1 and flag_tmp_2: # If we have (bc) and (bd) then we have (bcd)
476
                                               # The following achieves b->c->d->b
477
                                               S6 = swap(S3, 3, 4) # (bc)
                                              S6 = swap(S6, 3, 5) # (bd), here in the 3 index lies c but we name it b
478
                still, notice we use S6
                                              if S == S6:
479
480
                                                      flag = True
                                               # The following achieves b->d->c->b
481
                                              S7 = swap(S3, 3, 5) \# (bd)
482
483
                                              S7 = swap(S7, 3, 4) # (bc), here in the 3 index lies d but we name it b
                still, notice we use S7
                                              if S == S7:
484
485
                                                      flag = True
486
                                       if permutation_boolean(M, E, 4, 5): # If we have (cd)
487
488
                                               S8 = swap(S3, 4, 5)
489
                                               if S == S8:
490
                                                      flag = True
491
492
```

```
493
        else: # Now we consider the case where (pq) is available
494
495
            # We can either try the above or omit using R1 and just use (pq)
496
            # Whenever we check for non-chirality we can can also perform a pi rotation in the plane
497
          that contains the
            # 3-axis and has normal the final_state_particle_12 we matched in the 1-2 plane (usually
498
          this is a unless a has
            # no 1,2 components)
499
500
            # The following is repeating the above but incorporating the (pq) degree of freedom
501
502
            if (a[1] == 0 and a[2] == 0) or (a == 0):
503
504
                if (b[1] == 0 and b[2] == 0) or (b == 0):
505
506
                     if (c[1] == 0 and c[2] == 0) or (c == 0):
507
508
                         flag = True
509
510
                     else: # Here we consider that a,b are either e3 collinear or 0, only c and d are
511
         in the 1-2 plane
512
                         # We can map c_12 to its original or d_12 to the original c_12 and swap (cd)
513
          if they can be
                         # permuted.
514
515
                         # Since a and b are fixed by R1 = e1e3 we only want to consider permutations
516
         (cd)
                         \ensuremath{\texttt{\#}} Remember that idx 2 corresponds to a and idx 3 corresponds to b in S
517
                         permute_with_c_new = list([idx for idx in permute_with_c if (idx != 2) and (
518
        idx != 3)])
519
520
                         R1 = e1 * e3
521
                         S1 = rotate(S_parity, R1)
522
523
                         for idx in permute_with_c_new+[4]: # The index of c is 4 in the list S
524
525
526
                             # Map x_12_rotated to c_12_original
527
528
                             x = S1[idx]
                             x_{12} = x - x[3] * e3
c_{12} = c - c[3] * e3
529
530
531
                             n = (x_{12} + c_{12}).normal()
                             if n == 0: # If x_12 and c_12 are anti-parallel then we need a pi
532
        rotation
                                 R2 = e1 * e2
                             else: # Otherwise we construct the rotor as usual with the form R = (
534
        final destination)*n
535
                                 R2 = c_{12.normal()*n}
536
                             S2 = rotate(S1, R2)
                             S3 = swap(S2, idx, 4)
537
538
                             if S == S3:
539
540
                                 flag = True
541
                             # Now we can try the pi rotation in the plane v-e3 where v is
542
        perpendicular c_12 and e3
543
                             v = (-I*(e3^c_12)).normal() # Cross product in geometric algebra, I is
544
        the pseudoscalar, v = e3 \times c_{-}12
                             R3 = e3^v
545
546
                             S4 = rotate(S3, R3)
547
                             S5 = swap(S4, 0, 1)
548
549
                             if S == S5:
550
                                  flag = True
551
```

```
552
553
                 else: # Here we consider that a is collinear with e3 or is 0 but b is not
554
555
                     # We map x_12 to b_12_original and consider permutations between (cd), where
        x_12 can be (b,c,d)_12
556
                     permute_with_b_new = list([idx for idx in permute_with_b if (idx != 2)])
557
558
559
                     R1 = e1 * e3
560
                     S1 = rotate(S_parity, R1)
561
562
                     for idx in permute_with_b_new + [3]: # The index of b is 3 in the list S
563
564
                         # Map x_12_rotated to b_12_original
565
566
                         x = S1[idx]
567
                         x_12 = x - x[3] * e3

b_12 = b - b[3] * e3
568
569
                         n = (x_12 + b_12).normal()
if n = 0: # If x_12 and b_12 are anti-parallel then we need a pi rotation
570
571
                             R2 = e1 * e2
572
                         else: # Otherwise we construct the rotor as usual with the form R = (final
573
        destination)*n
                            R2 = b_{12.normal()} * n
574
                         S2 = rotate(S1, R2)
575
                         S3 = swap(S2, idx, 3)
576
577
                         if S == S3:
578
                             flag = True
579
580
581
                         v = (-I * (e3 ^ b_12)).normal() # Cross product in geometric algebra, I is
        the pseudoscalar, v = e3 \times c_{-12} (pq) degree of freedom, rotation by pi in the plane e3-v
582
583
584
                         S4 = rotate(S3, R3)
585
                         S5 = swap(S4, 0, 1)
586
                         if S == S5:
587
588
                              flag = True
589
590
                         if permutation_boolean(M, E, 4, 5): # If (cd) is possible
591
592
                             S6 = swap(S3, 4, 5)
593
                             if S == S6:
594
595
                                 flag = True
596
597
                             S7 = rotate(S6, R3)
598
599
                              S8 = swap(S7, 0, 1)
600
                              if S == S8:
601
                                  flag = True
602
603
            else: # Here we consider that a is not collinear with e3 and not 0
604
605
                 # We need to map x_12 to a_12_original and consider permutations (bcd)
606
607
                R1 = e1 * e3
608
609
                S1 = rotate(S_parity, R1)
610
611
                for idx in permute_with_a + [2]: # The index of a is 2 in the list S
612
613
                     # Map x_12_rotated to a_12_original
614
615
                     x = S1[idx]
616
                     x_{12} = x - x[3] * e3
617
```

```
618
                     a_{12} = a - a[3] * e3
                     n = (x_{12} + a_{12}).normal()
619
620
                     if n == 0: # If x_12 and a_12 are anti-parallel then we need a pi rotation
621
                         R2 = e1 * e2
                     else: # Otherwise we construct the rotor as usual with the form R = (final
622
        destination)*n
                        R2 = a_{12.normal}() * n
623
                     S2 = rotate(S1, R2)
624
                     S3 = swap(S2, idx, 2)
625
626
                     if S == S3:
627
                         flag = True
628
629
                     v = (-I * (e3 ^ a_12)).normal() # Cross product in geometric algebra, I is the
630
        pseudoscalar, v = e3 \times c_{12}
                     R3 = e3 v # (pq) degree of freedom, rotation by pi in the plane e3-v
631
632
                     S4 = rotate(S3, R3)
633
                     S5 = swap(S4, 0, 1)
634
635
                     if S == S5:
636
                         flag = True
637
638
                     flag_tmp_1 = permutation_boolean(M, E, 3, 4) # This checks if (bc) is available
639
640
641
                     if flag_tmp_1:
                         S6 = swap(S3, 3, 4)
if S == S6:
642
643
                             flag = True
644
645
                         S7 = rotate(S6, R3)
646
                         S8 = swap(S7, 0, 1)
647
648
649
                         if S == S8:
650
                             flag = True
651
                     flag_tmp_2 = permutation_boolean(M, E, 3, 5) # This checks if (bd) is available
652
653
654
                     if flag_tmp_2:
                         S9 = swap(S3, 3, 5)
if S == S9:
655
656
657
                            flag = True
658
                         S10 = rotate(S9, R3)
659
                         S11 = swap(S10, 0, 1)
660
661
                         if S == S11:
662
                             flag = True
663
664
665
666
                     if flag_tmp_1 and flag_tmp_2: # If we have (bc) and (bd) then we have (bcd)
667
                         # The following achieves b->c->d->b
                         S12 = swap(S3, 3, 4) # (bc)
668
                         S13 = swap(S12, 3, 5) # (bd), here in the 3 index lies c but we name it b
669
        still, notice we use S6
                         if S == S13:
670
671
                             flag = True
                         S14 = rotate(S13, R3)
672
673
                         S15 = swap(S14, 0, 1)
674
                         if S == S15:
675
676
                             flag = True
                         # The following achieves b->d->c->b
677
                         S16 = swap(S3, 3, 5) # (bd)
S17 = swap(S16, 3, 4) # (bc), here in the 3 index lies d but we name it b
678
679
        still, notice we use S7
                         if S == S17:
680
                             flag = True
681
                         S18 = rotate(S17, R3)
682
```

```
S19 = swap(S18, 0, 1)
683
684
685
                          if S == S19:
686
                              flag = True
687
                     if permutation_boolean(M, E, 4, 5): # If we have (cd)
688
689
                          S20 = swap(S3, 4, 5)
690
                          if S == S20:
691
                             flag = True
692
                          S21 = rotate(S20, R3)
693
                          S22 = swap(S21, 0, 1)
694
695
                          if S == S22:
696
                              flag = True
697
698
699
            # The following is omitting R1 and just uses (pq), it again incorporates the (pq) degree
700
          of freedom
701
            if (a[1] == 0 and a[2] == 0) or (a == 0):
702
703
                 if (b[1] == 0 and b[2] == 0) or (b == 0):
704
705
                     if (c[1] == 0 and c[2] == 0) or (c == 0):
706
707
                          flag = True
708
709
                     else: # Here we consider that a,b are either e3 collinear or 0, only c and d
710
         are in the 1-2 plane
711
                         # We can map c_{12} to its original or d_{12} to the original c_{12} and swap (cd)
712
          if they can be
713
                         # permuted.
714
715
                          # Since a and b are fixed by R1 = e1e3 we only want to consider permutations
          (cd)
                          \ensuremath{\texttt{\#}} Remember that idx 2 corresponds to a and idx 3 corresponds to b in S
716
717
                          permute_with_c_new = list([idx for idx in permute_with_c if (idx != 2) and (
         idx != 3)])
718
719
                         S1 = swap(S_parity, 0, 1)
720
721
                          for idx in permute_with_c_new + [4]: # The index of c is 4 in the list S
722
723
                              # Map x_12_rotated to c_12_original
724
                              x = S1[idx]
725
                              x_12 = x - x[3] * e3
c_12 = c - c[3] * e3
726
727
                              n = (x_12 + c_12).normal()
if n == 0: # If x_12 and c_12 are anti-parallel then we need a pi
728
729
         rotation
730
                                  R2 = e1 * e2
                              else: # Otherwise we construct the rotor as usual with the form R = (
731
         final destination)*n
                                  R2 = c_12.normal() * n
732
                              S2 = rotate(S1, R2)
733
734
                              S3 = swap(S2, idx, 4)
735
                              if S == S3:
736
737
                                  flag = True
738
                              # Now we can try the pi rotation in the plane v-e3 where v is
739
         perpendicular c_12 and e3
740
          v = (-I * (e3 ^ c_12)).normal() # Cross product in geometric algebra, I is the pseudoscalar, v = e3 x c_12 R3 = e3 ^ v
741
742
```

```
743
                              S4 = rotate(S3, R3)
744
745
                              S5 = swap(S4, 0, 1)
746
                              if S == S5:
747
                                  flag = True
748
749
750
                 else: # Here we consider that a is collinear with e3 or is 0 but b is not
751
752
                     # We map x_12 to b_12_original and consider permutations between (cd), where
        x_12 can be (b,c,d)_12
753
                     permute_with_b_new = list([idx for idx in permute_with_b if (idx != 2)])
754
755
                     S1 = swap(S_parity, 0, 1)
756
757
                     for idx in permute_with_b_new + [3]: # The index of b is 3 in the list S
758
759
                          # Map x_12_rotated to b_12_original
760
761
                         x = S1[idx]
762
                         x_12 = x - x[3] * e3

b_12 = b - b[3] * e3
763
764
                         n = (x_12 + b_12).normal()
if n = 0: # If x_12 and b_12 are anti-parallel then we need a pi rotation
765
766
                              R2 = e1 * e2
767
                          else: # Otherwise we construct the rotor as usual with the form R = (final
768
         destination)*n
                             R2 = b_{12.normal()} * n
769
                         S2 = rotate(S1, R2)
S3 = swap(S2, idx, 3)
770
771
772
                          if S == S3:
773
                              flag = True
774
775
                         v = (-I * (e3 ^ b_12)).normal() # Cross product in geometric algebra, I is
776
        the pseudoscalar, v = e3 x c_12
R3 = e3 ^ v # (pq) degree of freedom, rotation by pi in the plane e3-v
777
778
779
                          S4 = rotate(S3, R3)
780
                         S5 = swap(S4, 0, 1)
781
782
                          if S == S5:
783
                              flag = True
784
                         if permutation_boolean(M, E, 4, 5): # If (cd) is possible
785
786
                              S6 = swap(S3, 4, 5)
787
788
789
                              if S == S6:
790
                                  flag = True
791
                              S7 = rotate(S6, R3)
792
                              S8 = swap(S7, 0, 1)
793
794
                              if S == S8:
795
                                   flag = True
796
797
798
            else: # Here we consider that a is not collinear with e3 and not 0
799
                 # We need to map x_{12} to a_{12} original and consider permutations (bcd)
800
801
                 S1 = swap(S_parity, 0, 1)
802
803
                 for idx in permute_with_a + [2]: # The index of a is 2 in the list S
804
805
                     # Map x_12_rotated to a_12_original
806
807
                     x = S1[idx]
808
```

```
809
                     x_{12} = x - x[3] * e3
                     a_{12} = a - a[3] * e3
810
                     if n = (x_12 + a_12).normal()
if n = 0: # If x_12 and a_12 are anti-parallel then we need a pi rotation
811
812
                         R2 = e1 * e2
813
                     else: # Otherwise we construct the rotor as usual with the form R = (final
814
         destination)*n
                         R2 = a_{12.normal()} * n
815
                     S2 = rotate(S1, R2)
816
                     S3 = swap(S2, idx, 2)
817
818
                     if S == S3:
819
                         flag = True
820
821
                     v = (-I * (e3 ^ a_12)).normal() # Cross product in geometric algebra, I is the
822
        pseudoscalar, v = e3 \times c_{12}
                     R3 = e3 \cdot v \# (pq) degree of freedom, rotation by pi in the plane e3-v
823
824
                     S4 = rotate(S3, R3)
825
                     S5 = swap(S4, 0, 1)
826
827
                     if S == S5:
828
                          flag = True
829
830
                     flag_tmp_1 = permutation_boolean(M, E, 3, 4) # This checks if (bc) is available
831
832
833
                     if flag_tmp_1:
                         S6 = swap(S3, 3, 4)
if S == S6:
834
835
                              flag = True
836
837
838
                          S7 = rotate(S6, R3)
                          S8 = swap(S7, 0, 1)
839
840
                          if S == S8:
841
842
                              flag = True
843
                     flag_tmp_2 = permutation_boolean(M, E, 3, 5) # This checks if (bd) is available
844
845
846
                     if flag_tmp_2:
                          S9 = swap(S3, 3, 5)
if S == S9:
847
848
849
                              flag = True
850
                          S10 = rotate(S9, R3)
                          S11 = swap(S10, 0, 1)
851
852
853
                          if S == S11:
854
                              flag = True
855
856
                     if flag_tmp_1 and flag_tmp_2: # If we have (bc) and (bd) then we have (bcd)
857
                          # The following achieves b->c->d->b
858
                          S12 = swap(S3, 3, 4) \# (bc)
                          S13 = swap(S12, 3, 5) # (bd), here in the 3 index lies c but we name it b
859
         still, notice we use S6
                         if S == S13:
860
861
                             flag = True
                          S14 = rotate(S13, R3)
862
                          S15 = swap(S14, 0, 1)
863
864
                          if S == S15:
865
866
                              flag = True
                          # The following achieves b->d->c->b
867
                         S16 = swap(S3, 3, 5) # (bd)
S17 = swap(S16, 3, 4) # (bc), here in the 3 index lies d but we name it b
868
869
         still, notice we use S7
                         if S == S17:
870
                          flag = True
S18 = rotate(S17, R3)
871
872
                          S19 = swap(S18, 0, 1)
873
```

```
874
                         if S == S19:
875
876
                             flag = True
877
                     if permutation_boolean(M, E, 4, 5): # If we have (cd)
878
879
                         S20 = swap(S3, 4, 5)
880
                         if S == S20:
881
                            flag = True
882
                         S21 = rotate(S20, R3)
883
                        S22 = swap(S21, 0, 1)
884
885
                         if S == S22:
886
                             flag = True
887
888
889
       if flag:
            non chiral states.append([S, E])
890
        else:
891
            chiral_states.append([S, E])
892
893
       return non_chiral_states, chiral_states
894
895
896 # chiral_states = []
897 # non_chiral_states = []
898 #
899 # for _ in range(10):
900 #
901 #
          non_chiral_states_tmp , chiral_states_tmp = chirality_test()
902 #
          non_chiral_states += non_chiral_states_tmp
          chiral_states += chiral_states_tmp
903 #
904 #
905 # # The first slot is incremented for every true and the second for every false
906 # non_chiral_evaluation_on_logic_statement = [0, 0]
907 # chiral_evaluation_on_logic_statement = [0, 0]
908 #
909 # for non_chiral_state in non_chiral_states:
910 #
          flag = logic_statement_true_for_non_chiral(non_chiral_state[0], non_chiral_state[1])
911 #
          if flag:
912 #
              non_chiral_evaluation_on_logic_statement[0] += 1
913 #
          else:
914 #
             non_chiral_evaluation_on_logic_statement[1] += 1
915 #
916 # for chiral_state in chiral_states:
917 #
          flag = logic_statement_true_for_non_chiral(chiral_state[0], chiral_state[1])
918 #
          if flag:
919 #
              chiral_evaluation_on_logic_statement[0] += 1
920 #
          else:
921 #
              chiral_evaluation_on_logic_statement[1] += 1
922 #
923 # x = ['True', 'False']
924 # height_non_chiral = [non_chiral_evaluation_on_logic_statement[0],
        non_chiral_evaluation_on_logic_statement[1]]
925 # height_chiral = [chiral_evaluation_on_logic_statement[0], chiral_evaluation_on_logic_statement
        [1]]
926 #
227 # plt.bar(x, height_non_chiral, color = 'k', width = 0.1)
228 # plt.title('Non-chiral states evaluated on the logic statement\nwhich is true iff the input is
       non-chiral')
929 # plt.ylabel('Frequency')
930 # plt.show()
931 # # plt.savefig('non_chiral_collision_logic_statement_test.pdf', bbox_inches='tight')
932 # #
933 # plt.bar(x, height_chiral, color = 'k', width = 0.1)
934 # plt.title('Chiral states evaluated on the logic statement\nwhich is true iff the input is non-
        chiral')
935 # plt.ylabel('Frequency')
936 # plt.show()
937 # plt.savefig('chiral_collision_logic_statement_test.pdf', bbox_inches='tight')
938
```

Code file: non_collision_one_massive_algorithm.py

```
1 import time
2 from numpy import pi, cos, sin, e, tan, arctan
3 from clifford.g3 import blades
4 import matplotlib.pyplot as plt
5 from mpl_toolkits.mplot3d import Axes3D
6 import numpy as np
7 from random import uniform, seed, randint
8 from sympy import LeviCivita as eps
9 from main import parity, rotate, energy, epsilon, Gram_det_2
10 from pytest import approx
11
12 # Works only for a,b,c,d != 0 (it is very unlikely that any one will be randomly generated in
       momentum 0)
13
14 e1, e2, e3 = blades['e1'], blades['e2'], blades['e3']
15 I = e1^e2^e3
16
17 def dot(a,b):
       dot = a[1]*b[1] + a[2]*b[2] + a[3]*b[3]
18
       return dot
19
20
21 def multivec_to_vec(a):
       return np.array([a[1], a[2], a[3]])
22
23
24 def swap(S,idx_1,idx_2):
25
26
       tmp = S[idx_1]
       S[idx_1] = S[idx_2]
S[idx_2] = tmp
27
28
29
30
       return S
31
32 def logic_statement_true_for_non_chiral(S, E, mp, mq):
33
34
       p = np.array([mp, 0, 0, 0])
       q = np.array([mq, 0, 0, 0])
35
36
       a = multivec_to_vec(S[0])
37
       a = np.insert(a, 0, E[0])
38
       b = multivec_to_vec(S[1])
       b = np.insert(b, 0, E[1])
39
       c = multivec_to_vec(S[2])
40
       c = np.insert(c, 0, E[2])
41
       d = multivec_to_vec(S[3])
42
       d = np.insert(d, 0, E[3])
43
       RF = p + q
44
45
46
       case_1 = ((epsilon(a, b, c, RF) == approx(0)) and (epsilon(a, b, d, RF) == approx(0)) and (
       epsilon(b, c, d, RF) == approx(0)) and (
                    epsilon(a, c, d, RF) == approx(0)))
47
48
       case_2 = ((dot(a,a) = approx(dot(b,b))) and (not (a == b).all()) and (Gram_det_2(a,RF,a,RF))
49
           approx(Gram_det_2(b,RF,b,RF))) and (Gram_det_2(a,RF,c,RF) == approx((Gram_det_2(b,RF,c,
       RF)))) and (Gram_det_2(a,RF,d,RF) == approx(Gram_det_2(b,RF,d,RF))))
50
       def case_2_symmetry(a,b,c,d):
           return ((dot(a,a) == approx(dot(b,b))) and (not (a == b).all()) and (Gram_det_2(a,RF,a,
52
       RF) == approx(Gram_det_2(b,RF,b,RF))) and (Gram_det_2(a,RF,c,RF) == approx((Gram_det_2(b,RF
        ,c,RF) == 0))) and (Gram_det_2(a,RF,d,RF) == approx(Gram_det_2(b,RF,d,RF))))
53
       case_3 = case_2_symmetry(a,c,b,d)
54
       case_4 = case_2_symmetry(a,d,c,b)
55
       case_5 = case_2_symmetry(b,c,a,d)
56
57
       case_6 = case_2_symmetry(b,d,c,a)
       case_7 = case_2_symmetry(c,d,a,b)
58
59
```

```
case_8 = ((dot(a,a) == approx(dot(b,b))) and (dot(c,c) == approx(dot(d,d))) and (Gram_det_2(
 60
         a,RF,a,RF) == approx(Gram_det_2(b,RF,b,RF))) and (Gram_det_2(c,RF,c,RF) == approx(
Gram_det_2(d,RF,d,RF))) and ((((dot(a+b,a+b) == approx(4*dot(a,a)) == approx(4*dot(b,b))))
          and ((dot(c+d,c+d) == approx(4*dot(c,c)) == approx(4*dot(d,d))))) or ((Gram_det_2(a+b,RF,c-
         d,RF) == approx(0)) or (not (c == d).all()))))
 61
         def case_8_symmetry(a,b,c,d):
 62
             return ((dot(a,a) == approx(dot(b,b))) and (dot(c,c) == approx(dot(d,d))) and (
 63
          Gram_det_2(a,RF,a,RF) == approx(Gram_det_2(b,RF,b,RF))) and (Gram_det_2(c,RF,c,RF) ==
          approx(Gram_det_2(d,RF,d,RF))) and ((((dot(a+b,a+b) == approx(4*dot(a,a)) == approx(4*dot(b
          ,b)))) and ((dot(c+d,c+d) == approx(4*dot(c,c)) == approx(4*dot(d,d))))) or ((Gram_det_2(a+
         b,RF,c-d,RF) == approx(0)) or (not (c == d).all()))))
 64
 65
         case 9 = case 8 symmetry(a.c.b.d)
         case_10 = case_8_symmetry(a,d,b,c)
 66
 67
         \texttt{case_19} = ((\texttt{dot}(\texttt{a},\texttt{a}) \texttt{=} \texttt{approx}(\texttt{dot}(\texttt{b},\texttt{b})) \texttt{=} \texttt{approx}(\texttt{dot}(\texttt{c},\texttt{c})) \texttt{=} \texttt{approx}(\texttt{dot}(\texttt{d},\texttt{d}))) \texttt{ and } (
 68
         Gram_det_2(a,RF,a,RF) == approx(Gram_det_2(b,RF,b,RF)) == approx(Gram_det_2(c,RF,c,RF)) ==
         approx(Gram_det_2(d,RF,d,RF))) and approx((Gram_det_2(a - c,RF,b - d,RF) == 0)))
 69
         def case_19_symmetry(a,b,c,d):
 70
         return ((dot(a,a) == approx(dot(b,b)) == approx(dot(c,c)) == approx(dot(d,d))) and (
Gram_det_2(a,RF,a,RF) == approx(Gram_det_2(b,RF,b,RF)) == approx(Gram_det_2(c,RF,c,RF)) ==
approx(Gram_det_2(d,RF,d,RF))) and approx((Gram_det_2(a - c,RF,b - d,RF) == 0)))
 71
 72
 73
         case_20 = case_19_symmetry(a,b,d,c)
         case_21 = case_19_symmetry(a,c,b,d)
 74
         case_22 = case_19_symmetry(a,c,d,b)
case_23 = case_19_symmetry(a,d,c,b)
 75
 76
         case_24 = case_19_symmetry(a,d,b,c)
 77
 78
 79
         return (case_1 or case_2 or case_3 or case_4 or case_5 or case_6 or case_7 or case_8 or
         case_9 or case_10
 80
                  or case_19 or case_20 or case_21 or case_22 or case_23 or case_24)
 81
 82 def construct_state():
 83
         B = (uniform(-10, 10) * (e1 ^ e2) + uniform(-10, 10) * (e1 ^ e3) + uniform(-10, 10) * (e2 ^
 84
         e3)).normal()
         R = (e ^ (uniform(0, 2 * pi) * B)).normal()
 85
 86
 87
         rdm = randint(0, 4)
 88
         if rdm == 0:
 89
              ma, mb, mc, md = randint(0, 10), randint(0, 10), randint(0, 10), randint(0, 10)
 90
              a = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
 91
              b = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
 92
              c = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
d = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
 93
 94
 95
 96
         # Type of non-chiral (checked) (ab)
 97
         if rdm == 1:
 98
             ma, mb, mc, md = 1, 1, 2, 3
 99
              a = e1
100
              b = e2
              c = e3
              d = (-e3)
102
103
104
         # Type of non-chiral (checked) (ab)(cd)
         if rdm == 2:
105
106
              ma, mb, mc, md = 1, 1, 2, 2
              n = uniform(-10, 10)*e1 + uniform(-10, 10)*e2 + uniform(-10, 10)*e3
107
              n = n.normal()
108
              a = uniform(-10, 10)*e1 + uniform(-10, 10)*e2 + uniform(-10, 10)*e3
109
              b = -n*a*n
110
              c = uniform(-10, 10)*e1 + uniform(-10, 10)*e2 + uniform(-10, 10)*e3
111
              d = -n * c * n
112
113
114 # Type of non-chiral (checked) (abc)
```

```
115
        if rdm == 3:
            ma, mb, mc, md = 1, 1, 1, 3
116
            mag = uniform(-10, 10)
117
            a = mag*e1 + mag*e2
b = mag*e1 - mag*e2
118
119
            c = -mag*e1 + mag*e2
120
            d = mag * e1 - mag * e2
121
122
        # Type of non-chiral (checked) (abcd)
123
        if rdm == 4:
124
            ma, mb, mc, md = 1, 1, 1, 1
a = R*(-e1 + e3)*~R
b = R*(e1 + e2)*~R
c = R*(-e1 - e3)*~R
125
126
127
128
            d = R*(e1 - e2)*^{R}
129
130
        Ea, Eb, Ec, Ed = energy(ma, a), energy(mb, b), energy(mc, c), energy(md, d)
131
132
        M = [ma, mb, mc, md]
133
       E = [Ea, Eb, Ec, Ed]
S = [a, b, c, d]
134
135
136
        print(rdm)
137
138
        return S, E, M
139
140
141 def permute_with_idx(M, E, idx_to_permute):
142
        same_mass_with_idx = [idx for idx in range(len(M)) if M[idx] == M[idx_to_permute] and idx !=
143
         idx_to_permute]
        same_energy_with_idx = [idx for idx in range(len(E)) if E[idx] == approx(E[idx_to_permute])
144
        and idx != idx_to_permute]
145
146
        return list(set(same_mass_with_idx) and set(same_energy_with_idx))
147
148 def permutation_boolean(M, E, idx_1, idx_2):
149
        if (M[idx_1] == M[idx_2]) and (E[idx_1] == E[idx_2]):
150
151
            return True
152
        else:
153
            return False
154
155 def chirality_test():
156
157
        chiral_states = []
158
        non_chiral_states = []
159
        S, E, M = construct_state()
160
        a, b, c, d = S[0], S[1], S[2], S[3] # p and q are 0 so we do not carry them around in the S
161
        list
162
163
        # These lists hold indices (as they appear in S) of the particles that can be permuted with
        a,b,c and d respectively
        permute_with_a = permute_with_idx(M, E, 0)
164
        permute_with_c = permute_with_idx(M, E, 2)
165
166
        permute_with_d = permute_with_idx(M, E, 3)
167
168
169
        S_parity = parity(S) # Perform parity on the set of momenta
170
171
        flag = False # The flag is set to true if the state is non-chiral
172
        for idx in permute_with_a+[0]: # For every x that can be permuted with a, map x to a and
173
        perform (ax)
174
175
            x = S_parity[idx]
            n = a+x
176
            if n == 0: # If a and x are collinear we construct any v perpendicular to a and do a pi
177
        rotation in the plane av
```

```
178
                if a[2] != 0 or a[3] != 0:
                    v = -I*(a^e1) # Cross product a x e1 in geometric algebra, I is the pseudoscalar
179
         I = e1e2e3
180
                else:
                    v = -I*(a^2)
181
                R1 = (a^v).normal()
182
            else:
183
                R1 = a.normal()*n.normal()
184
185
            S1 = rotate(S_parity, R1)
186
            S2 = swap(S1, 0, idx) # Performs (ax) where the index 0 corresponds to a in the S list
187
188
            # At this point a is fixed to its original state
189
190
            # Now we need to fix b in the plane perpendicular to a, if b has no component (a^b==0)
191
        there then we try c
192
            if a^b != 0: # If b is not collinear to a then it has components in the plane
193
        perpendicular to a
194
                for idx_plane in permute_with_b + [1]:
195
196
                    if idx_plane == 0: # Since a is already fixed
197
198
                        continue
199
200
                    # If we have a plane P with its perpendicular being a and we have a vector y,
        then the component of y
                    \# in the plane P is given in geometric algebra by the rejection y_plane = a*(a^y
201
        )
202
203
                    b_plane = a*(a^b)
204
                    y = S2[idx_plane]
205
                    y_plane = a*(a^y)
206
207
                    \ensuremath{\texttt{\#}} If y is collinear with a then it has no component in the plane perpendicular
        to a, so even if it can
208
                    # be permuted with b, we cannot map y_plane to b_plane and then swap because
        y_plane is 0
209
210
                    if y_plane == 0:
211
                         continue
212
                    else: # Here we map y_plane to b_plane and perform (yb)
213
                        m = y_plane + b_plane
                         if m == 0: # In this case we need a pi rotation in this plane we are working
214
         in
215
                             # We construct another vector in this plane with the cross product a x
        b_plane
                             w_plane = -I*(a^b_plane)
216
                             R2 = (w_plane^b_plane).normal()
217
                         else:
218
219
                             R2 = b_plane.normal()*m.normal()
220
                    S3 = rotate(S2, R2) # Map y_plane to b_plane
221
                    S4 = swap(S3, 1, idx_plane) # Perform (yb)
222
223
                    if S == S4:
224
                        flag = True
225
226
227
                    if permutation_boolean(M, E, 2, 3): # If we can perform (cd)
                        S5 = swap(S4, 2, 3)
228
                         if S == S5:
229
                             flag = True
230
231
232
            elif a^c != 0:
233
234
                for idx_plane in permute_with_c + [2]:
235
236
                    # Since a and b are already fixed, b is fixed because we fixed a and to get into
237
```

```
this elif we need
                     # b to be collinear with a and hence when we fixed a we automatically fixed b
238
239
                     if idx_plane == 0 or idx_plane == 1:
240
                         continue
241
                    # If we have a plane P with its perpendicular being a and we have a vector y,
242
        then the component of y
                    \# in the plane P is given in geometric algebra by the rejection y_plane = a*(a^y)
243
        )
244
                    c_plane = a * (a ^ c)
245
                    y = S2[idx_plane]
246
                    y_plane = a * (a ^ y)
247
248
                    # If y is collinear with a then it has no component in the plane perpendicular
249
        to a, so even if it can
                    # be permuted with c, we cannot map y_plane to c_plane and then swap because
250
        y_plane is 0
251
                    if y_plane == 0:
252
253
                         continue
                     else: # Here we map y_plane to c_plane and perform (yc)
254
255
                         m = y_plane + c_plane
                         if m = 0: # In this case we need a pi rotation in this plane we are
256
        working in
257
                             # We construct another vector in this plane with the cross product a x
        c_plane
                            w_plane = -I * (a ^ c_plane)
R2 = (w_plane ^ c_plane).normal()
258
259
                         else:
260
                             R2 = c_plane.normal() * m.normal()
261
262
                    S6 = rotate(S2, R2) # Map y_plane to c_plane
S7 = swap(S6, 2, idx_plane) # Perform (yc)
263
264
265
266
                    if S == S7:
267
                         flag = True
268
                     if permutation_boolean(M, E, 1, 3): # If we can perform (bd)
269
270
                         S8 = swap(S7, 1, 3)
271
                         if S == S8:
272
                             flag = True
273
274
            else:
275
                flag = True # If a,b,c are collinear then the state is non-chiral
276
277
        if flag:
            non_chiral_states.append([S, E])
278
        else:
279
            chiral_states.append([S, E])
280
281
282
       return non_chiral_states, chiral_states
283
284 # non_chiral_states_list = []
285 # chiral_states_list = []
286 # for iterations in range(1000):
         S, E, M = construct_state()
287 #
         non_chiral_states, chiral_states = chirality_test()
288 #
289 #
         non_chiral_states_list += non_chiral_states
290 #
         chiral_states_list += chiral_states
291 #
292 # print(len(non_chiral_states_list), len(chiral_states_list))
293 #
294 # non_chiral_evaluation_on_logic_statement = [0, 0]
295 # for non_chiral_state in non_chiral_states_list:
         mp, mq = uniform(1, 10), uniform(1, 10)
296 #
297 #
         flag = logic_statement_true_for_non_chiral(non_chiral_state[0], non_chiral_state[1], mp,
        mq)
298 # if flag:
```

```
non_chiral_evaluation_on_logic_statement[0] += 1
299 #
300 #
           else:
301 #
               non_chiral_evaluation_on_logic_statement[1] += 1
302 #
303 # chiral_evaluation_on_logic_statement = [0, 0]
304 # for chiral_state in chiral_states_list:
305 #
          mp, mq = uniform(1, 10), uniform(1, 10)
306 #
           flag = logic_statement_true_for_non_chiral(chiral_state[0], chiral_state[1], mp, mq)
307 #
           if flag:
308 #
               chiral_evaluation_on_logic_statement[0] += 1
309 #
           else:
310 #
               chiral evaluation on logic statement[1] += 1
311 #
312 # x = ['True', 'False']
313 # height_non_chiral = [non_chiral_evaluation_on_logic_statement[0],
non_chiral_evaluation_on_logic_statement[1]]
314 # height_chiral = [chiral_evaluation_on_logic_statement[0], chiral_evaluation_on_logic_statement
         [1]]
315 #
316 # plt.bar(x, height_non_chiral, color = 'k', width = 0.1)
317 # plt.title('Non-chiral states evaluated on the logic statement\nwhich is true iff the input is
         non-chiral')
318 # plt.ylabel('Frequency')
319 # #plt.show()
320 # #plt.savefig('non_chiral_non_collision_logic_statement_test.pdf', bbox_inches='tight')
321 #
322 # plt.bar(x, height_chiral, color = 'k', width = 0.1)
323 # plt.title('Chiral states evaluated on the logic statement\nwhich is true iff the input is non-
        chiral')
324 # plt.ylabel('Frequency')
325 # #plt.show()
326 # plt.savefig('chiral_non_collision_logic_statement_test.pdf', bbox_inches='tight')
```

Code file: non_collision_massless_algorithm.py

```
1 import time
2 from numpy import pi, cos, sin, e, tan, arctan
3 from clifford.g3 import blades
4 import matplotlib.pyplot as plt
5 from mpl_toolkits.mplot3d import Axes3D
6 import numpy as np
7 from random import uniform, seed, randint
8 from sympy import LeviCivita as eps
9 from main import parity, rotate, energy, epsilon, Gram_det_2
10 from pytest import approx
12 e1, e2, e3 = blades['e1'], blades['e2'], blades['e3']
13 I = e1^{2}e3
14
15 def dot(a,b):
16
      dot = a[1]*b[1] + a[2]*b[2] + a[3]*b[3]
17
      return dot
18
19 def multivec_to_vec(a):
     return np.array([a[1], a[2], a[3]])
20
^{21}
22 def swap(S,idx_1,idx_2):
^{23}
24
       tmp = S[idx_1]
      S[idx_1] = S[idx_2]
25
      S[idx_2] = tmp
26
27
      return S
28
29
30 def sym_2_Gram_det(a,b):
      return Gram_det_2(a,b,a,b)
31
32
33 def logic statement true for non chiral(S. E):
34
```

```
p = multivec_to_vec(S[0])
36
                 p = np.insert(p, 0, E[0])
37
                 q = multivec_to_vec(S[1])
                 q = np.insert(q, 0, E[1])
38
                 a = multivec_to_vec(S[2])
39
40
                 a = np.insert(a, 0, E[2])
                 b = multivec_to_vec(S[3])
41
                 b = np.insert(b, 0, E[3])
42
                 c = multivec_to_vec(S[4])
43
                 c = np.insert(c, 0, E[4])
44
                 d = multivec_to_vec(S[5])
45
                 d = np.insert(d, 0, E[5])
46
                 RF = a + b + c + d
47
48
                 case_1 = (epsilon(a,b,p+q,RF) == epsilon(a,c,p+q,RF) == epsilon(a,d,p+q,RF) == epsilon(b,c,p
49
                  +q,RF) == epsilon(b,d,p+q,RF) == epsilon(c,d,p+q,RF) == 0)
50
                 case_2 = ((dot(a,a) == approx(dot(b,b))) and (Gram_det_2(a-b,RF,p+q,RF) == approx(0)) and (
51
                  sym_2_Gram_det(a, RF) == approx(sym_2_Gram_det(b, RF))))
52
                 def case_2_symmetry(a,b,c,d):
                            return ((dot(a,a) == dot(b,b)) and (Gram_det_2(a-b,RF,p+q,RF) == 0) and (sym_2_Gram_det(
54
                  a.RF) == svm 2 Gram det(b.RF)))
55
56
                 case_3 = case_2_symmetry(a, c, b, d)
57
                 case_4 = case_2_symmetry(a, d, c, b)
                 case_5 = case_2_symmetry(b, c, a, d)
58
59
                 case_6 = case_2_symmetry(b, d, a, c)
                  case_7 = case_2_symmetry(c, d, a, b)
60
61
                 \texttt{case_8} = ((\texttt{dot}(\texttt{a},\texttt{a}) \texttt{=} \texttt{approx}(\texttt{dot}(\texttt{b},\texttt{b}))) \texttt{ and } (\texttt{Gram\_det_2}(\texttt{a}-\texttt{b},\texttt{RF},\texttt{p+q},\texttt{RF}) \texttt{=} \texttt{approx}(0)) \texttt{ and } (\texttt{and} \texttt{and} \texttt{an
62
                   \texttt{sym_2}_\texttt{Gram\_det}(\texttt{a},\texttt{RF}) \ \texttt{=} \ \texttt{approx}(\texttt{sym_2}_\texttt{Gram\_det}(\texttt{b},\texttt{RF}))) \ \texttt{and} \ (\texttt{dot}(\texttt{c},\texttt{c}) \ \texttt{=} \ \texttt{approx}(\texttt{dot}(\texttt{d},\texttt{d})))
                   and (Gram_det_2(c-d,RF,p+q,RF) == approx(0)) and (sym_2_Gram_det(c,RF) == approx(
                   sym_2_Gram_det(d, RF)) and (Gram_det_2(a-b, RF, c+d, RF) == approx(0)))
64
                 def case_8_symmetry(a,b,c,d):
                   return ((dot(a,a) == approx(dot(b,b))) and (Gram_det_2(a-b,RF,p+q,RF) == approx(0)) and
(sym_2_Gram_det(a,RF) == approx(sym_2_Gram_det(b,RF))) and (dot(c,c) == approx(dot(d,d)))
65
                   and (Gram_det_2(c-d,RF,p+q,RF) == approx(0)) and (sym_2_Gram_det(c,RF) == approx(
                   sym_2_Gram_det(d, RF)) and (Gram_det_2(a-b, RF, c+d, RF) == approx(0)))
66
67
                  case_9 = case_8_symmetry(a,c,b,d)
68
                 case_10 = case_8_symmetry(a,d,b,c)
69
                  return (case_1 or case_2 or case_3 or case_4 or case_5 or case_6 or case_7 or case_8 or
70
                   case_9 or case_10)
71
72 def permute_with_idx(M, E, idx_to_permute):
73
                  same_mass_with_idx = [idx for idx in range(len(M)) if M[idx] == M[idx_to_permute] and idx !=
74
                     idx_to_permute and idx != 0 and idx != 1]
                  same_energy_with_idx = [idx for idx in range(len(E)) if E[idx] == approx(E[idx_to_permute])
                   and idx != idx_to_permute]
76
77
                  return list(set(same_mass_with_idx) and set(same_energy_with_idx))
78
79 def permutation_boolean(M, E, idx_1, idx_2):
80
81
                  if (M[idx_1] == M[idx_2]) and (E[idx_1] == E[idx_2]):
                           return True
82
83
                 else:
                           return False
84
85
86 def construct_state():
87
                 rdm = randint(0, 0)
88
89
                 if rdm == 0:
90
                         mp, mq, ma, mb, mc, md = 0, 0, randint(0, 10), randint(0, 10), randint(0, 10), randint
91
```

```
(0, 10)
                        p = uniform(-10, 10) * e3
 92
                        q = uniform(-10, 10) * e3
 93
                        a = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
 94
                        b = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
c = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
 95
 96
                        d = -a - b - c
 97
 98
               if rdm == 1:
 99
                        # non chiral
100
                        mp, mq, ma, mb, mc, md = 0, 0, randint(0, 10), randint(0, 10), randint(0, 10), randint
                 (0, 10)
                       p = uniform(-10, 10) * e3
102
                        q = uniform(-10, 10) * e3
103
                        a = uniform(-10, 10) * e1 + uniform(-10, 10) * e3
104
                       b = uniform(-10, 10) * e1 + uniform(-10, 10) * e3
c = uniform(-10, 10) * e1 + uniform(-10, 10) * e3
106
                        d = -a - b - c
108
               if rdm == 2:
109
                        # (ab) non chiral
110
                        mp, mq, ma, mb, mc, md = 0, 0, 1, 1, randint(0, 10), randint(0, 10)
111
                        p = uniform(-10, 10) * e3
112
                        q = uniform(-10, 10)*e3
a = 4 * e1 + 5 * e2 + 3 * e3
113
114
                        B = (uniform(-10, 10) * (e1 ^ e2) + uniform(-10, 10) * (e1 ^ e3) + uniform(-10, 10) * (
115
                 e2 ^ e3)).normal()
                       R = e ^ (uniform(0, 2 * pi) * B)
b = -5 * e1 + 4 * e2 + 3 * e3
116
117
                        c = a+b
118
119
                        d = -c
120
121
               if rdm == 3:
122
                        # (ab)(cd) non chiral
                        mp, mq, ma, mb, mc, md = 0, 0, 1, 1, 2, 2
123
124
                        p = uniform(-10, 10) * e3
125
                        q = uniform(-10, 10) * e3
                        angle_a = uniform(0,pi/5)
angle_c = uniform(0, pi / 5)
126
127
                        a = cos(angle_a)*e1 + sin(angle_a)*e2 + uniform(-10, 10)*e3
128
                       b = sin(angle_a)*e1 + cos(angle_a)*e2 + a[3]*e3
c = -cos(angle_c)*e1 - sin(angle_c)*e2 - uniform(-10, 10)*e3
129
130
131
                        d = -sin(angle_c)*e1 - cos(angle_c)*e2 + c[3]*e3
               Ep, Eq, Ea, Eb, Ec, Ed = energy(mp, p), energy(mq, q), energy(ma, a), energy(mb, b), energy(mb, b)
                mc, c), energy(md, d)
134
               M = [mp, mq, ma, mb, mc, md]
E = [Ep, Eq, Ea, Eb, Ec, Ed]
136
               S = [p, q, a, b, c, d]
137
138
139
               return S, E, M
140
141 def chirality_test():
142
               chiral_states = []
143
144
               non_chiral_states = []
145
               S, E, M = construct_state()
146
               p, q, a, b, c, d = S[0], S[1], S[2], S[3], S[4], S[5]
147
148
               # These lists hold indices (as they appear in S) of the particles that can be permuted with
149
               a,b,c and d respectively
               permute_with_a = permute_with_idx(M, E, 2)
               permute_with_b = permute_with_idx(M, E, 3)
permute_with_c = permute_with_idx(M, E, 4)
151
152
               permute_with_d = permute_with_idx(M, E, 5)
153
154
               S_parity = parity(S) # Perform parity on the set of momenta
```

```
156
157
        flag = False # The flag is set to true if the state is non-chiral
158
159
        R1 = e1 * e3
       S1 = rotate(S_parity, R1) # Now p and q are fixed back to their original state
160
161
        if (a[1] != 0) or (a[2] != 0): # If a has components in the 1-2 plane
162
163
           for idx in permute_with_a + [2]: # For every x that can be permuted with a, map x to a
164
        and perform (ax)
165
                x = S1[idx]
166
                x_{12} = x - x[3] * e3
a_{12} = a - a[3] * e3
167
168
169
                n = a_{12} + x_{12}
170
171
                if n == 0:
172
173
                    R2 = e1 * e2
174
                else:
176
177
                    R2 = a_12.normal()*n.normal()
178
179
                S2 = rotate(S1, R2)
180
                S3 = swap(S2, 2, idx)
181
182
                if S == S3:
183
                    flag = True
184
185
        \# The degrees of freedom left now that a is fixed to its original state are permutations between b,c,d
186
187
                flag_tmp_1 = permutation_boolean(M, E, 3, 4) # This checks if (bc) is available
188
189
190
                if flag_tmp_1:
191
                    S4 = swap(S3, 3, 4)
                    if S == S4:
192
193
                        flag = True
194
                flag_tmp_2 = permutation_boolean(M, E, 3, 5) # This checks if (bd) is available
195
196
197
                if flag_tmp_2:
198
                    S5 = swap(S3, 3, 5)
                    if S == S5:
199
200
                        flag = True
201
                flag_tmp_3 = permutation_boolean(M, E, 4, 5) # If we have (cd)
202
203
204
                if flag_tmp_3:
205
                    S6 = swap(S3, 4, 5)
                    if S == S6:
206
                        flag = True
207
208
                if flag_tmp_1 and flag_tmp_2: # If we have (bc) and (bd) then we have (bcd)
209
                    # The following achieves b->c->d->b
210
                    S7 = swap(S3, 3, 4) \# (bc)
211
212
                    S8 = swap(S7, 3, 5) # (bd), here in the 3 index lies c but we name it b still,
        notice we use S6
                    if S == S8:
213
                        flag = True
214
215
                    # The following achieves b->d->c->b
216
                    217
218
         notice we use S7
                    if S == S10:
219
                        flag = True
220
```

```
221
        elif (b[1] != 0) or (b[2] != 0): # To get here we asserted that a is collinear with e3 so
222
        fixed by R1
223
            for idx in permute_with_b + [3]: # For every x that can be permuted with b, map x to b
224
         and perform (bx)
225
                 if idx == 2: # We do not want permutations with a since a is fixed by R1 when
226
        collinear with e3
227
                     continue
228
                 x = S1[idx]
229
                 x_12 = x - x[3] * e3

b_12 = b - b[3] * e3
230
231
232
                 n = b_{12} + x_{12}
233
234
                 if n == 0:
235
236
                     R2 = e1 * e2
237
238
                 else:
239
240
                     R2 = b_12.normal() * n.normal()
241
242
                 S2 = rotate(S1, R2)
243
                 S3 = swap(S2, 3, idx)
244
245
                 if S == S3:
246
                     flag = True
247
248
        \ensuremath{\texttt{\#}} The degrees of freedom left now that b is fixed to its original state are permutations between c,d
249
250
                 flag_tmp_1 = permutation_boolean(M, E, 4, 5) # This checks if (cd) is available
251
252
253
                 if flag_tmp_1:
                     S4 = swap(S3, 4, 5)
254
                     if S == S4:
255
256
                         flag = True
257
258
        elif (c[1] != 0) or (c[2] != 0): # To get here we asserted that a,b are collinear with e3 so
          fixed by R1
259
260
            for idx in permute_with_c + [4]: # For every x that can be permuted with c, map x to c
         and perform (cx)
261
                 if (idx == 2) or (idx == 3): # We do not want permutations with a,b since a,b are
262
         fixed by R1
263
                     continue
264
265
                 x = S1[idx]
                 x_12 = x - x[3] * e3
c_12 = c - c[3] * e3
266
267
268
                 n = c_{12} + x_{12}
269
270
                 if n == 0:
271
272
273
                     R2 = e1 * e2
274
275
                 else:
276
                     R2 = c_12.normal() * n.normal()
277
278
                 S2 = rotate(S1, R2)
279
                 S3 = swap(S2, 4, idx)
280
281
                 if S == S3:
```

```
283
                    flag = True
284
285
       if flag:
286
           non_chiral_states.append([S, E])
        else:
287
288
            chiral_states.append([S, E])
289
290
       return non_chiral_states, chiral_states
291
292 # non_chiral_states_list = []
293 # chiral_states_list = []
294 # for iterations in range(1000):
        S, E, M = construct_state()
295 #
296 #
         non_chiral_states, chiral_states = chirality_test()
         non_chiral_states_list += non_chiral_states
297 #
         chiral_states_list += chiral_states
298 #
299 #
300 # print(len(non_chiral_states_list), len(chiral_states_list))
301 #
302 # non_chiral_evaluation_on_logic_statement = [0, 0]
303 # for non_chiral_state in non_chiral_states_list:
         flag = logic_statement_true_for_non_chiral(non_chiral_state[0], non_chiral_state[1])
304 #
305 #
         if flag:
306 #
             non_chiral_evaluation_on_logic_statement[0] += 1
307 #
          else:
308 #
              non_chiral_evaluation_on_logic_statement[1] += 1
309 #
310 # chiral_evaluation_on_logic_statement = [0, 0]
311 # for chiral_state in chiral_states_list:
         flag = logic_statement_true_for_non_chiral(chiral_state[0], chiral_state[1])
312 #
313 #
         if flag:
314 #
             chiral_evaluation_on_logic_statement[0] += 1
315 #
          else:
316 #
              chiral_evaluation_on_logic_statement[1] += 1
317 #
318 # x = ['True', 'False']
319 # height_non_chiral = [non_chiral_evaluation_on_logic_statement[0],
        non_chiral_evaluation_on_logic_statement[1]]
320 # height_chiral = [chiral_evaluation_on_logic_statement[0], chiral_evaluation_on_logic_statement
        [1]]
321 #
322 # plt.bar(x, height_non_chiral, color = 'k', width = 0.1)
323 # plt.title('Non-chiral states evaluated on the logic statement\nwhich is true iff the input is
       non-chiral')
324 # plt.ylabel('Frequency')
325 # #plt.show()
326 # plt.savefig('non_chiral_non_collision_massless_logic_statement_test.pdf', bbox_inches='tight')
327 #
328 # plt.bar(x, height_chiral, color = 'k', width = 0.1)
329 # plt.title('Chiral states evaluated on the logic statement\nwhich is true iff the input is non-
        chiral')
330 # plt.ylabel('Frequency')
331 # plt.show()
332 # plt.savefig('chiral_non_collision_massless_logic_statement_test.pdf', bbox_inches='tight')
333
334 print(chirality_test())
```

Code file: non_collision_zeros_algorithm.py

```
import time
from numpy import pi, cos, sin, e, tan, arctan
from clifford.g3 import blades
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
import numpy as np
from random import uniform, seed, randint
from sympy import LeviCivita as eps
from main import parity, rotate, energy, epsilon, Gram_det_2
from pytest import approx
```

```
11
12 # Works only for a,b,c,d != 0 (it is very unlikely that any one will be randomly generated in
                     momentum 0)
13
14 e1, e2, e3 = blades['e1'], blades['e2'], blades['e3']
15 I = e1^e2^e3
16
17 def dot(a,b):
                     dot = a[1]*b[1] + a[2]*b[2] + a[3]*b[3]
18
                     return dot
19
20
21 def multivec to vec(a):
                    return np.array([a[1], a[2], a[3]])
22
23
24 def swap(S,idx_1,idx_2):
25
                     tmp = S[idx_1]
26
                    S[idx_1] = S[idx_2]
S[idx_2] = tmp
27
28
29
                    return S
30
31
32 def sym_2_Gram_det(a,b):
                    return Gram_det_2(a,b,a,b)
33
34
35 def logic_statement_true_for_non_chiral(S, E):
36
                     a = multivec_to_vec(S[0])
37
38
                     a = np.insert(a, 0, E[0])
                     b = multivec_to_vec(S[1])
39
40
                    b = np.insert(b, 0, E[1])
                     c = multivec_to_vec(S[2])
41
 42
                     c = np.insert(c, 0, E[2])
                     d = multivec_to_vec(S[3])
 43
 44
                     d = np.insert(d, 0, E[3])
                    RF = a+b+c+d
 45
 46
 47
                    case_1 = (Gram_det_2(a, RF, a, RF) == approx(0))
 48
 49
                    case_2 = (dot(a+b+c+d, a+b+c+d) == approx(0))
 50
 51
                    case_3 = (epsilon(b,c,d,RF) == approx(0))
 52
                     case_4 = ((dot(b,b) == dot(c,c)) and (Gram_det_2(b-c,RF,a,RF) == 0) and (sym_2_Gram_det(b,RF))
                      ) == sym_2_Gram_det(c,RF)))
54
                      case_5 = ((dot(c,c) == dot(d,d)) and (Gram_det_2(c-d,RF,a,RF) == 0) and (sym_2_Gram_det(c,RF)) and (
 55
                     ) == sym_2_Gram_det(d,RF)))
 56
                      case_6 = ((dot(d,d) == dot(b,b)) and (Gram_det_2(d-b,RF,a,RF) == 0) and (sym_2_Gram_det(d,RF)) and (
57
                      ) == sym_2_Gram_det(b,RF)))
 58
                      return (case_1 or case_2 or case_3 or case_4 or case_5 or case_6)
 59
60
61 def permute_with_idx(M, E, idx_to_permute):
62
                     same_mass_with_idx = [idx for idx in range(len(M)) if M[idx] == M[idx_to_permute] and idx !=
63
                         idx_to_permute and idx != 0 and idx != 1]
                     same_energy_with_idx = [idx for idx in range(len(E)) if E[idx] == approx(E[idx_to_permute])
64
                      and idx != idx_to_permute]
65
                     return list(set(same_mass_with_idx) and set(same_energy_with_idx))
66
67
68 def permutation_boolean(M, E, idx_1, idx_2):
69
                     if (M[idx_1] == M[idx_2]) and (E[idx_1] == E[idx_2]):
70
                                return True
71
                     else:
72
 73 return False
```

```
74
 75 def construct_state():
 76
 77
         rdm = randint(0, 2)
 78
         if rdm == 0:
 79
             ma, mb, mc, md = randint(0, 10), randint(0, 10), randint(0, 10), randint(0, 10)
 80
              a = uniform(-10, 10) * e3
b = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
 81
 82
              c = uniform(-10, 10) * e1 + uniform(-10, 10) * e2 + uniform(-10, 10) * e3
 83
              d = -a-b-c
 84
 85
        if rdm == 1:
 86
              # This is the no permutation non-chiral case
 87
              ma, mb, mc, md = randint(0, 10), randint(0, 10), randint(0, 10), randint(0, 10)
a = uniform(-10, 10) * e3
b = e1 + e2 + uniform(-10, 10)*e3
c = -e1 - e2 + uniform(-10, 10)*e3
 88
 89
 90
 91
              d = -a-b-c
 92
 93
        if rdm == 2:
 94
              # Permute 2 non chiral case
 95
             # Permute 2 non chiral case
ma, mb, mc, md = 1, 1, 1, 1
a = uniform(-10, 10) * e3
angle = uniform(0, pi / 5)
b = sin(angle)*e1 + cos(angle)*e2 + uniform(-10, 10)*e3
c = cos(angle)*e1 + sin(angle)*e2 + b[3]*e3
d = cosbcc
 96
 97
 98
99
100
              d = -a-b-c
102
         Ea, Eb, Ec, Ed = energy(ma, a), energy(mb, b), energy(mc, c), energy(md, d)
103
104
         M = [ma, mb, mc, md]
E = [Ea, Eb, Ec, Ed]
105
106
         S = [a, b, c, d]
107
108
109
         return S, E, M
110
111 def chirality_test():
112
113
         chiral_states = []
114
         non_chiral_states = []
115
116
         S, E, M = construct_state()
117
         a, b, c, d = S[0], S[1], S[2], S[3]
118
119
         permute_with_b = permute_with_idx(M, E, 1)
120
         permute_with_c = permute_with_idx(M, E, 2)
121
         S_parity = parity(S) # Perform parity on the set of momenta
122
123
124
         flag = False # The flag is set to true if the state is non-chiral
125
         R1 = e1 * e3
126
         S1 = rotate(S_parity, R1) # Now a is fixed back to their original state
127
128
         if (b[1] != 0) or (b[2] != 0): # if b has components in the 1-2 plane
129
130
              for idx in permute_with_b + [1]:
131
132
                   if idx == 0:
133
134
                        continue
135
                   x = S1[idx]
136
                   x_{12} = x - x[3] * e3

b_{12} = b - b[3] * e3
137
138
139
                   n = b_{12} + x_{12}
140
141
               if n == 0:
```

```
143
                       R2 = e1 * e2
144
145
146
                  else:
147
                       R2 = b_12.normal()*n.normal()
148
149
                  S2 = rotate(S1, R2)
                  S3 = swap(S2, 1, idx) # Index 1 corresponds to b
151
152
                  if S == S3:
                      flag = True
154
                  if permutation_boolean(M, E, 2, 3): # If we can permute (cd)
156
                      S4 = swap(S3, 2, 3)
157
                       if S == S4:
158
                           flag = True
159
160
        elif (c[1] != 0) or (c[2] != 0):
161
162
             for idx in permute_with_c + [2]:
163
164
                  if idx == 0 or idx == 1:
165
166
                       continue
167
168
                  x = S1[idx]
                  x_12 = x - x[3] * e3
c_12 = c - c[3] * e3
169
170
                  n = c_{12} + x_{12}
172
173
174
                  if n == 0:
175
176
                      R2 = e1 * e2
177
178
                  else:
179
                      R2 = c_{12.normal()} * n.normal()
180
181
182
                  S2 = rotate(S1, R2)
                  S3 = swap(S2, 2, idx) # Index 2 corresponds to c
183
184
185
                  if S == S3:
186
                       flag = True
187
188
        if flag:
189
             non_chiral_states.append([S, E])
        else:
190
191
             chiral_states.append([S, E])
192
193
        return non_chiral_states, chiral_states
194
195 # non_chiral_states_list = []
196 # chiral_states_list = []
197 # for iterations in range(1000):
         S, E, M = construct_state()
198 #
          non_chiral_states, chiral_states = chirality_test()
non_chiral_states_list += non_chiral_states
199 #
200 #
201 #
          chiral_states_list += chiral_states
202 #
203 # print(len(non_chiral_states_list), len(chiral_states_list))
204 #
205 # non_chiral_evaluation_on_logic_statement = [0, 0]
206 # for non_chiral_state in non_chiral_states_list:
207 # mp, mq = uniform(1, 10), uniform(1, 10)
208 # flag = logic_statement_true_for_non_chiral(non_chiral_state[0], non_chiral_state[1])
209 #
          if flag:
210 #
               non_chiral_evaluation_on_logic_statement[0] += 1
           else:
211 #
```

```
non_chiral_evaluation_on_logic_statement[1] += 1
212 #
213 #
214 # chiral_evaluation_on_logic_statement = [0, 0]
215 # for chiral_state in chiral_states_list:
      mp, mq = uniform(1, 10), uniform(1, 10)
flag = logic_statement_true_for_non_chiral(chiral_state[0], chiral_state[1])
216 #
217 #
218 #
          if flag:
219 #
               chiral_evaluation_on_logic_statement[0] += 1
220 #
           else:
221 #
                chiral_evaluation_on_logic_statement[1] += 1
222 #
223 # x = ['True', 'False']
224 # height_non_chiral = [non_chiral_evaluation_on_logic_statement[0],
         non_chiral_evaluation_on_logic_statement[1]]
225 # height_chiral = [chiral_evaluation_on_logic_statement[0], chiral_evaluation_on_logic_statement
         [1]]
226 #
227 # plt.bar(x, height_non_chiral, color = 'k', width = 0.1)
228 # plt.title('Non-chiral states evaluated on the logic statement\nwhich is true iff the input is
         non-chiral')
229 # plt.ylabel('Frequency')
230 # #plt.show()
231 # plt.savefig('non_chiral_non_collision_logic_statement_test.pdf', bbox_inches='tight')
232 #
233 # plt.bar(x, height_chiral, color = 'k', width = 0.1)
234 # plt.title('Chiral states evaluated on the logic statement\nwhich is true iff the input is non-
         chiral')
235 # plt.ylabel('Frequency')
236 # plt.show()
237 # plt.savefig('chiral_non_collision_logic_statement_test.pdf', bbox_inches='tight')
238
239 print(chirality_test())
```