

E04MZF – NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

E04MZF reads data for a sparse linear programming or quadratic programming problem from an external file which is in standard or compatible MPSX input format.

2 Specification

```

SUBROUTINE E04MZF(INFILE, MAXN, MAXM, MAXNNZ, XBLDEF, XBUDEF,
1             MPLST, N, M, NNZ, IOBJ, NCOLH, A, HA, KA, BL,
2             BU, START, NAMES, NNAME, CRNAME, XS, ISTATE,
3             IFAIL)
  INTEGER
1     INFILE, MAXN, MAXM, MAXNNZ, N, M, NNZ, IOBJ,
2     NCOLH, HA(MAXNNZ), KA(MAXN+1), NNAME,
3     ISTATE(MAXN+MAXM), IFAIL
  real
1     XBLDEF, XBUDEF, A(MAXNNZ), BL(MAXN+MAXM),
2     BU(MAXN+MAXM), XS(MAXN+MAXM)
  CHARACTER*1
1     START
  CHARACTER*8
1     NAMES(5), CRNAME(MAXN+MAXM)
  LOGICAL
1     MPLST

```

3 Description

E04MZF reads linear programming (LP) or quadratic programming (QP) problem data from an external file which is prepared in standard or compatible MPSX [1] input format and then initializes n (the number of variables), m (the number of general linear constraints), the m by n matrix A , and the vectors l , u and c (stored in row IOBJ of A) for use with E04NKF, which is designed to solve problems of the form

$$\underset{x \in R^n}{\text{minimize}} \quad c^T x + \frac{1}{2} x^T H x \quad \text{subject to} \quad l \leq \begin{Bmatrix} x \\ Ax \end{Bmatrix} \leq u.$$

For LP problems, $H = 0$. For QP problems, you must set $NCOLH > 0$ (see Section 5) and provide a subroutine to E04NKF to compute Hx for any given vector x . (This is illustrated in Section 9.) The optional parameter **Maximize** may be used to specify an alternative problem in which the objective function is maximized. The document for E04NKF should be consulted for further details.

MPSX input format

The input file of data may only contain two types of lines:

- (1) Indicator lines (specifying the type of data which is to follow).
- (2) Data lines (specifying the actual data).

The input file must not contain any blank lines. Any characters beyond column 80 are ignored. Indicator lines must not contain leading blank characters (in other words they must begin in column 1). The following displays the order in which the indicator lines must appear in the file:

```

NAME          user-supplied name
ROWS
  data line(s)
COLUMNS
  data line(s)
RHS
  data line(s)
RANGES      (optional)
  data line(s)

```

BOUNDS (optional)
 data line(s)
 ENDDATA

The ‘user-supplied name’ specifies a name for the problem and must occupy columns 15–22. The name can either be blank or up to a maximum of 8 characters.

A data line follows the same fixed format made up of fields defined below. The contents of the fields may have different significance depending upon the section of data in which they appear.

	Field 1	Field 2	Field 3	Field 4	Field 5	Field 6
Columns	2–3	5–12	15–22	25–36	40–47	50–61
Contents	Code	Name	Name	Value	Name	Value

The names and codes consist of ‘alphanumeric’ characters (i.e., a–z, A–Z, 0–9, +, –, asterisk (*), blank (), colon (:), dollar sign (\$) or full stop (.) only) and the names must not contain leading blank characters. Values are read using Fortran format E12.0. This allows values to be entered in several equivalent forms. For example, 1.2345678, 1.2345678E+0, 123.45678E–2 and 12345678E–07 all represent the same number. It is safest to include an explicit decimal point.

Note that in order to ensure numeric values are interpreted as intended, they should be *right-justified* in the 12-character field, with no trailing blanks. This is because in some situations trailing blanks may be interpreted as zeros and this can dramatically affect the interpretation of the value. This is relevant if the value contains an exponent, or if it contains neither an exponent nor an explicit decimal point. For example, the fields

```
%%%1.23E-2%
%%%%%%%%123%%
```

may be interpreted as 1.23E–20 and 12300 respectively (where % denotes a blank). The actual behaviour is system-dependent.

Comment lines are allowed in the data file. These must have an asterisk (*) in column 1 and any characters in columns 2–80. In any data line, a dollar sign (\$) as the first character in field 3 or 5 indicates that the information from that point through column 80 consists of comments.

Columns outside the six fields must be blank, except for columns 72–80, whose contents are ignored by the routine. These columns may be used to enter a sequence number. A non-blank character outside the predefined six fields and columns 72–80 is considered to be a major error (IFAIL = 13; see Section 6), unless it is part of a comment.

ROWS Data Lines

These lines specify row (constraint) names and their inequality types (i.e., =, ≥ or ≤).

Field 1: defines the constraint type. It may be in column 2 or column 3.
 N free row, that is no constraint. It may be used to define the objective row.
 G greater than or equal to (i.e., ≥).
 L less than or equal to (i.e., ≤).
 E exactly equal to (i.e., =).
 Field 2: defines the row name.

Row type N stands for ‘Not binding’, also known as ‘Free’. It can be used to define the objective row. The objective row is a free row that specifies the vector c in the linear objective term $c^T x$. It is taken to be the first free row, unless some other free row name is specified by the NAMES array (see Section 5). Note that c is assumed to be zero if (for example) the line

```
%N%DUMMYROW
```

(where % denotes a blank) appears in the ROWS section of the MPSX data file, and the row name DUMMYROW is omitted from the COLUMNS section.

COLUMNS Data Lines

These lines specify the names to be assigned to the variables (columns) in the general linear constraint matrix A , and define, in terms of column vectors, the actual values of the corresponding matrix elements.

Field 1: blank (ignored)

Field 2: gives the name of the column associated with the elements specified in the following fields.

Field 3: contains the name of a row.

Field 4: used in conjunction with field 3 contains the value of the matrix element.

Field 5: is optional (may be used like field 3).

Field 6: is optional (may be used like field 4).

Note that only the non-zero elements of A and c need to be specified in the COLUMNS section, as any zero elements of A are removed and any unspecified elements of c are assumed to be zero. In addition, any non-zero elements in the j th column of A must be grouped together before those in the $(j + 1)$ th column, for $j = 1, 2, \dots, n - 1$. Non-zero elements within a column may however appear in any order.

RHS Data Lines

This section specifies the right-hand side values of the general linear constraint matrix A (if any). The lines specify the name to be given to the right-hand side (RHS) vector along with the numerical values of the elements of the vector, which may appear in any order. The data lines have exactly the same format as the COLUMNS data lines, except that the column name is replaced by the RHS name. Only the non-zero elements need be specified. Note that this section may be empty, in which case the RHS vector is assumed to be zero.

RANGES Data Lines (optional)

Ranges are used for constraints of the form $l \leq Ax \leq u$, where both l and u are finite. The range of the constraint is $r = u - l$. Either l or u must be specified in the RHS section and r must be defined in this section. The data lines have exactly the same format as the COLUMNS data lines, except that the column name is replaced by the RANGE name.

BOUNDS Data Lines (optional)

These lines specify limits on the values of the variables (l and u in $l \leq x \leq u$). If the variable is not specified in the bound set then it is automatically assumed to lie between default lower and upper bounds (usually 0 and $+\infty$). Like an RHS column which is given a name, the set of variables in one bound set is also given a name.

Field 1:	specifies the type of bound or defines the variable type.
LO	lower bound
UP	upper bound
FX	fixed variable
FR	free variable ($-\infty$ to $+\infty$)
MI	lower bound is $-\infty$
PL	upper bound is $+\infty$. This is the default variable type.
Field 2:	identifies a name for the bound set.
Field 3:	identifies the column name of the variable belonging to this set.
Field 4:	identifies the value of the bound; this has a numerical value only in association with LO, UP, FX in field 1, otherwise it is blank.
Field 5:	is blank and ignored.
Field 6:	is blank and ignored.

Note that if RANGES and BOUNDS sections are both present, the RANGES section must appear first.

4 References

- [1] (1971) MPSX – Mathematical programming system *Program Number 5734 XM4* IBM Trade Corporation, New York

5 Parameters

- 1:** INFILE — INTEGER *Input*
On entry: the unit number associated with the MPSX data file.
Constraint: $0 \leq \text{INFILE} \leq 99$.
- 2:** MAXN — INTEGER *Input*
On entry: an upper limit for the number of variables in the problem.
Constraint: $\text{MAXN} \geq 1$.
- 3:** MAXM — INTEGER *Input*
On entry: an upper limit for the number of constraints (including the objective row) in the problem.
Constraint: $\text{MAXM} \geq 1$.
- 4:** MAXNNZ — INTEGER *Input*
On entry: an upper limit for the number of non-zeros (including the objective row) in the problem.
Constraint: $\text{MAXNNZ} \geq 1$.
- 5:** XBLDEF — *real* *Input*
On entry: the default lower bound to be used for the variables in the problem when none is specified in the BOUNDS section of the MPSX data file. For a standard LP or QP problem XBLDEF would normally be set to zero.
- 6:** XBUDEF — *real* *Input*
On entry: the default upper bound to be used for the variables in the problem when none is specified in the BOUNDS section of the MPSX data file. For a standard LP or QP problem XBUDEF would normally be set to ‘infinity’ (i.e., $\text{XBUDEF} \geq 10^{20}$).
Constraint: $\text{XBUDEF} \geq \text{XBLDEF}$.
- 7:** MPLST — LOGICAL *Input*
On entry: if MPLST = .TRUE., then a listing of the input data is sent to the current advisory message unit (as defined by X04ABF). This can be useful for debugging the MPSX data file. If MPLST = .FALSE., then no listing is produced.
- 8:** N — INTEGER *Output*
On exit: n , the actual number of variables in the problem.
- 9:** M — INTEGER *Output*
On exit: m , the actual number of general linear constraints in the problem (including the objective row).
- 10:** NNZ — INTEGER *Output*
On exit: the actual number of non-zeros in the problem (including the objective row).
- 11:** IOBJ — INTEGER *Output*
On exit: if IOBJ > 0, row IOBJ of A is a free row containing the non-zero coefficients of the vector c . If IOBJ = 0, the coefficients of c are assumed to be zero. If IOBJ = -1, no such row was found and the routine terminates with IFAIL = 4 or 5 (see Section 6).
- 12:** NCOLH — INTEGER *Output*
On exit: NCOLH = 0. For QP problems, NCOLH is the number of leading non-zero columns of the Hessian matrix H and must therefore be set > 0 prior to calling E04NKF.

13: A(MAXNNZ) — *real* array *Output*
On exit: the non-zero elements of A , ordered by increasing column index.

14: HA(MAXNNZ) — INTEGER array *Output*
On exit: the row indices of the non-zero elements stored in A .

15: KA(MAXN+1) — INTEGER array *Output*
On exit: a set of pointers to the beginning of each column of A . More precisely, $KA(i)$ contains the index in A of the start of the i th column, for $i = 1, 2, \dots, N$. Note that $KA(1) = 1$ and $KA(N+1) = NNZ+1$.

16: BL(MAXN+MAXM) — *real* array *Output*

17: BU(MAXN+MAXM) — *real* array *Output*

On exit: BL contains the vector l (the lower bounds) and BU contains the vector u (the upper bounds), for all the variables and constraints in the following order. The first N elements of each array contain the bounds on the variables x and the next M elements contain the bounds for the linear objective term $c^T x$ and the general linear constraints Ax (if any). Note that an ‘infinite’ lower bound is indicated by $BL(j) = -1.0E+20$, an ‘infinite’ upper bound by $BU(j) = 1.0E+20$ and an equality constraint by $BL(j) = BU(j)$. (The lower bound for $c^T x$, stored in $BL(N+IOBJ)$, is set to $-XBUEDEF$. The corresponding upper bound, stored in $BU(N+IOBJ)$, is set to $XBUEDEF$.)

Note that E04MZF uses an ‘infinite’ bound size of 10^{20} in the definition of l and u . In other words, any element of u greater than or equal to 10^{20} will be regarded as $+\infty$ (and similarly any element of l less than or equal to -10^{20} will be regarded as $-\infty$). If this value is deemed to be ‘inappropriate’, you are recommended to reset the value of the optional parameter **Infinite Bound Size** and make any necessary changes to BL and/or BU prior to calling E04NKF.

18: START — CHARACTER*1 *Output*
On exit: START = ‘C’ and an internal Crash procedure will be used by E04NKF to choose an initial basis.

19: NAMES(5) — CHARACTER*8 *Input/Output*
On entry: a set of names associated with the MPSX form of the problem as follows:

NAMES(1) must contain either the name of the problem or be blank;

NAMES(2) must contain either the name of the objective row or be blank (in which case the first objective free row is used);

NAMES(3) must contain either the name of the RHS set to be used or be blank (in which case the first RHS set is used);

NAMES(4) must contain either the name of the RANGE set to be used or be blank (in which case the first RANGE set (if any) is used);

NAMES(5) must contain either the name of the BOUNDS set to be used or be blank (in which case the first BOUNDS set (if any) is used).

On exit: a set of names associated with the problem as defined in the MPSX data file as follows:

NAMES(1) contains the name of the problem (or blank if none);

NAMES(2) contains the name of the objective row (or blank if none);

NAMES(3) contains the name of the RHS set (or blank if none);

NAMES(4) contains the name of the RANGE set (or blank if none);

NAMES(5) contains the name of the BOUNDS set (or blank if none).

20: NNAME — INTEGER *Output*
On exit: $n + m$, the total number of variables and constraints in the problem.

- 21:** CRNAME(MAXN+MAXM) — CHARACTER*8 array *Output*
On exit: the MPSX names of all the variables and constraints in the problem in the following order. The first N elements contain the MPSX names for the variables and the next M elements contain the MPSX names for the objective row and general linear constraints (if any). (The MPSX name for the objective row is stored in CRNAME(N+IOBJ).)
- 22:** XS(MAXN+MAXM) — *real* array *Output*
On exit: a set of initial values for the variables and constraints in the problem. More precisely, $XS(j) = \min(\max(0.0, BL(j)), BU(j))$, for $j = 1, 2, \dots, NNAME$.
- 23:** ISTATE(MAXN+MAXM) — INTEGER array *Output*
On exit: a set of initial states for the variables and constraints in the problem. More precisely, $ISTATE(j) = 1$ if $XS(j) = BU(j)$ and 0 otherwise, for $j = 1, 2, \dots, NNAME$.
- 24:** IFAIL — INTEGER *Input/Output*
On entry: IFAIL must be set to 0, -1 or 1. For users not familiar with this parameter (described in Chapter P01) the recommended value is 0.
On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors detected by the routine:

IFAIL = 1

There are too many rows present in the data file. Increase MAXM by at least $(M - MAXM)$ and rerun E04MZF.

IFAIL = 2

There are too many columns present in the data file. Increase MAXN by at least $(N - MAXN)$ and rerun E04MZF.

IFAIL = 3

There are too many non-zeros present in the data file. Increase MAXNNZ by at least $(NNZ - MAXNNZ)$ and rerun E04MZF.

The following error exits (apart from IFAIL = 17) are caused by having either a corrupt or a non-standard MPSX data file. Refer to Section 3 for a detailed description of the MPSX format which can be read by E04MZF. If MPST = .TRUE., the last line of printed output refers to the line in the MPSX data file which contains the reported error.

IFAIL = 4

The objective row was not found. There must be at least one row in the ROWS section with row type N for the objective row.

IFAIL = 5

An unknown objective row name was detected in the ROWS section.

IFAIL = 6

There are no rows specified in the ROWS section.

IFAIL = 7

An illegal constraint type was detected in the ROWS section. The constraint type must be either N, L, G or E.

IFAIL = 8

An illegal row name was detected in the ROWS section. Names must be made up of ‘alphanumeric’ characters (see Section 3) with no leading blanks.

IFAIL = 9

An illegal column name was detected in the COLUMNS section. Names must be made up of ‘alphanumeric’ characters (see Section 3) with no leading blanks.

IFAIL = 10

An illegal bound type was detected in the BOUNDS section. The bound type must be either LO, UP, FX, FR, MI or PL.

IFAIL = 11

An unknown column name was detected in the BOUNDS section. All the column names must be specified in the COLUMNS section.

IFAIL = 12

The last line in the data file does not contain the ENDDATA line indicator.

IFAIL = 13

An illegal data line was detected in the file. This line is neither a comment line nor a valid data line.

IFAIL = 14

An unknown row name was detected in COLUMNS or RHS or RANGES section. All the row names must be specified in the ROWS section.

IFAIL = 15

There were no columns specified in the COLUMNS section.

IFAIL = 16

The name of the RHS, RANGE or BOUNDS set to be used was not found in the data file.

IFAIL = 17

On entry, INFILE < 0,
or INFILE > 99,
or MAXN < 1,
or MAXM < 1,
or MAXNNZ < 1,
or XBLDEF > XBUDEF.

7 Accuracy

Not applicable.

8 Further Comments

None.

9 Example

To solve the quadratic programming problem

minimize

$$c^T x + \frac{1}{2} x^T H x$$

subject to

$$\begin{aligned} l &\leq Ax \leq u, \\ -2 &\leq x \leq 2, \end{aligned}$$

where

$$c = \begin{pmatrix} -4.0 \\ -1.0 \\ -1.0 \\ -1.0 \\ -1.0 \\ -1.0 \\ -1.0 \\ -0.1 \\ -0.3 \end{pmatrix}, \quad H = \begin{pmatrix} 2 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 2 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 2 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 2 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \quad \text{NCOLH} = 5,$$

$$A = \begin{pmatrix} 1.0 & 1.0 & 1.0 & 1.0 & 1.0 & 1.0 & 1.0 & 1.0 & 4.0 \\ 1.0 & 2.0 & 3.0 & 4.0 & -2.0 & 1.0 & 1.0 & 1.0 & 1.0 \\ 1.0 & -1.0 & 1.0 & -1.0 & 1.0 & 1.0 & 1.0 & 1.0 & 1.0 \end{pmatrix}, \quad l = \begin{pmatrix} -2.0 \\ -2.0 \\ -2.0 \end{pmatrix} \quad \text{and} \quad u = \begin{pmatrix} 1.5 \\ 1.5 \\ 4.0 \end{pmatrix}.$$

The optimal solution (to five figures) is

$$x^* = (2.0, -0.23333, -0.26667, -0.3, -0.1, 2.0, 2.0, -1.7777, -0.45555)^T.$$

Three bound constraints and two general linear constraints are active at the solution. Note that, although the Hessian matrix is positive semi-definite, the point x^* is unique.

The MPSX representation of the problem is given in Section 9.2.

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```

*      E04MZF Example Program Text.
*      Mark 18 Release. NAG Copyright 1997.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER       (NIN=5,NOUT=6)
      INTEGER          MAXN, MAXM, MAXNNZ, LENIZ, LENZ
      PARAMETER       (MAXN=10000,MAXM=10000,MAXNNZ=100000,LENIZ=50000,
+                    LENZ=100000)
      real           ZERO, XBLDEF, XBUDEF
      PARAMETER       (ZERO=0.0e+0,XBLDEF=ZERO,XBUDEF=1.0e+20)
*      .. Local Scalars ..
      real           OBJ, SINF
      INTEGER          I, IFAIL, INFILE, INFORM, IOBJ, M, MINIZ, MINZ,
+                    N, NCOLH, NINF, NNAME, NNZ, NS
      LOGICAL          MPSLST
      CHARACTER        START
      CHARACTER*8      KBLANK
*      .. Local Arrays ..
      real           A(MAXNNZ), BL(MAXN+MAXM), BU(MAXN+MAXM),
+                    CLAMDA(MAXN+MAXM), XS(MAXN+MAXM), Z(LENZ)
      INTEGER          HA(MAXNNZ), ISTATE(MAXN+MAXM), IZ(LENIZ),

```



```

+          KA(MAXN+1)
CHARACTER*8  CRNAME(MAXN+MAXM), NAMES(5)
*   .. External Subroutines ..
EXTERNAL     E04MZF, E04NKF, E04NLF, E04NMF, QPHX, X04ABF
*   .. Data statements ..
DATA        KBLANK/'      '/
*   .. Executable Statements ..
WRITE (NOUT,*) 'E04MZF Example Program Results'
*   Skip heading in data file.
READ (NIN,*)

*
*   Initialize parameters.
*
INFILE = NIN
MPSLST = .FALSE.
DO 20 I = 1, 5
    NAMES(I) = KBLANK
20 CONTINUE

*
*   Convert the MPSX data file for use by E04NKF.
*
IFAIL = 0

*
CALL E04MZF(INFILE,MAXN,MAXM,MAXNNZ,XBLDEF,XBUDEF,MPSLST,N,M,NNZ,
+          IOBJ,NCOLH,A,HA,KA,BL,BU,START,NAMES,NNAME,CRNAME,XS,
+          ISTATE,IFAIL)
*
*
IF (IFAIL.EQ.0) THEN
*
*   Set two options using E04NMF.
*
CALL E04NMF(' Check Frequency = 10 ')
*
CALL E04NMF(' Crash Tolerance = 0.05 ')
*
*   Set the unit number for advisory messages to NOUT.
*
CALL X04ABF(1,NOUT)
*
*   Read the options file.
*
CALL E04NLF(NIN,INFORM)
*
IF (INFORM.NE.0) THEN
+   WRITE (NOUT,99999) 'E04NLF terminated with INFORM = ',
+   INFORM
+   STOP
END IF
*
*   Reset the value of NCOLH.
*
NCOLH = 5
*
*   Solve the QP problem.
*
IFAIL = -1
*

```

```

      CALL EO4NKF(N,M,NNZ,IOBJ,NCOLH,QPHX,A,HA,KA,BL,BU,START,NAMES,
+             NNAME,CRNAME,NS,XS,ISTATE,MINIZ,MINZ,NINF,SINF,OBJ,
+             CLAMDA,IZ,LENIZ,Z,LENZ,IFAIL)
*
      END IF
*
      STOP
*
99999 FORMAT (1X,A,I3)
      END
*
      SUBROUTINE QPHX(NSTATE,NCOLH,X,HX)
*
      Routine to compute H*x. (In this version of QPHX, the Hessian
*      matrix H is not referenced explicitly.)
*
      .. Parameters ..
      INTEGER          NOUT
      PARAMETER       (NOUT=6)
      real            TWO
      PARAMETER       (TWO=2.0e+0)
*
      .. Scalar Arguments ..
      INTEGER          NCOLH, NSTATE
*
      .. Array Arguments ..
      real            HX(NCOLH), X(NCOLH)
*
      .. Executable Statements ..
      IF (NSTATE.EQ.1) THEN
*
*         First entry.
*
*         WRITE (NOUT,99999) NCOLH
*
      END IF
*
*         Normal entry.
*
      HX(1) = TWO*X(1) + X(2) + X(3) + X(4) + X(5)
      HX(2) = X(1) + TWO*X(2) + X(3) + X(4) + X(5)
      HX(3) = X(1) + X(2) + TWO*X(3) + X(4) + X(5)
      HX(4) = X(1) + X(2) + X(3) + TWO*X(4) + X(5)
      HX(5) = X(1) + X(2) + X(3) + X(4) + TWO*X(5)
*
      IF (NSTATE.GE.2) THEN
*
*         Final entry.
*
*         WRITE (NOUT,99998)
*
      END IF
*
      RETURN
*
99999 FORMAT (/ ' This is the EO4NDF example.   NCOLH =',I4,','.')
99998 FORMAT (/ ' Finished the EO4NDF example.')
```

9.2 Program Data

Note. The MPSX data which is read by E04MZF begins with the **second** record of this data file; the first record is a caption which is read by the example program.

```

E04MZF Example Program Data
NAME          QP
ROWS
L   ..ROW1..
L   ..ROW2..
L   ..ROW3..
N   ..COST..
COLUMNS
...X1... ..ROW1..    1.0      ..ROW2..    1.0
...X1... ..ROW3..    1.0      ..COST..   -4.0
...X2... ..ROW1..    1.0      ..ROW2..    2.0
...X2... ..ROW3..   -1.0      ..COST..   -1.0
...X3... ..ROW1..    1.0      ..ROW2..    3.0
...X3... ..ROW3..    1.0      ..COST..   -1.0
...X4... ..ROW1..    1.0      ..ROW2..    4.0
...X4... ..ROW3..   -1.0      ..COST..   -1.0
...X5... ..ROW1..    1.0      ..ROW2..   -2.0
...X5... ..ROW3..    1.0      ..COST..   -1.0
...X6... ..ROW1..    1.0      ..ROW2..    1.0
...X6... ..ROW3..    1.0      ..COST..   -1.0
...X7... ..ROW1..    1.0      ..ROW2..    1.0
...X7... ..ROW3..    1.0      ..COST..   -1.0
...X8... ..ROW1..    1.0      ..ROW2..    1.0
...X8... ..ROW3..    1.0      ..COST..   -0.1
...X9... ..ROW1..    4.0      ..ROW2..    1.0
...X9... ..ROW3..    1.0      ..COST..   -0.3
RHS
RHS1      ..ROW1..    1.5
RHS1      ..ROW2..    1.5
RHS1      ..ROW3..    4.0
RANGES
RANGE1    ..ROW1..    3.5
RANGE1    ..ROW2..    3.5
RANGE1    ..ROW3..    6.0
BOUNDS
LO BOUND  ...X1...   -2.0
LO BOUND  ...X2...   -2.0
LO BOUND  ...X3...   -2.0
LO BOUND  ...X4...   -2.0
LO BOUND  ...X5...   -2.0
LO BOUND  ...X6...   -2.0
LO BOUND  ...X7...   -2.0
LO BOUND  ...X8...   -2.0
LO BOUND  ...X9...   -2.0
UP BOUND  ...X1...    2.0
UP BOUND  ...X2...    2.0
UP BOUND  ...X3...    2.0
UP BOUND  ...X4...    2.0
UP BOUND  ...X5...    2.0
UP BOUND  ...X6...    2.0
UP BOUND  ...X7...    2.0
UP BOUND  ...X8...    2.0
UP BOUND  ...X9...    2.0
ENDATA

```

```

Begin * Example options file for E04MZF
  Iteration Limit      = 25 * (Default = 65)
  Expand Frequency    = 1000 * (Default = 10000)
End

```

9.3 Program Results

E04MZF Example Program Results

Calls to E04NMF

```

Check Frequency = 10
Crash Tolerance = 0.05

```

OPTIONS file

```

Begin * Example options file for E04MZF
  Iteration Limit      = 25 * (Default = 65)
  Expand Frequency    = 1000 * (Default = 10000)
End

```

*** E04NKF

*** Start of NAG Library implementation details ***

```

Implementation title: Generalised Base Version
Precision: FORTRAN double precision
Product Code: FLBAS18D
Mark: 18A

```

*** End of NAG Library implementation details ***

Parameters

Frequencies.

```

Check frequency.....          10          Expand frequency.....          1000
Factorization frequency.      100

```

LP Parameters.

```

Scale tolerance..... 9.00E-01          Feasibility tolerance... 1.00E-06
Iteration limit.....          25          Scale option.....          2
Optimality tolerance.... 1.00E-06          Partial price.....          10
Crash tolerance..... 5.00E-02          Pivot tolerance..... 2.04E-11
Crash option.....          2

```

QP objective.

```

Objective variables.....          5          Hessian columns.....          5
Superbasics limit.....          6

```

Miscellaneous.

```

Variables.....          9          Linear constraints.....          4
LU factor tolerance.... 1.00E+02          LU update tolerance.... 1.00E+01
LU singularity tolerance 2.04E-11          Monitoring file.....          -1
EPS (machine precision). 1.11E-16          Print level.....          10

```

Infinite bound size..... 1.00E+20 Infinite step size..... 1.00E+20
 COLD start..... MINIMIZE.....

Workspace provided is IZ(50000), Z(100000).
 To start solving the problem we need IZ(237), Z(228).

Itn	Step	Ninf	Sinf/Objective	Norm rg
0	0.0E+00	0	0.000000E+00	0.0E+00

This is the E04NDF example. NCOLH = 5.

Itn 0 -- Factorize detected a singular Hessian.
 Rank = 5. Diag, min diag = 0.00E+00 3.31E-13.
 0 0.0E+00 0 0.000000E+00 6.3E+00
 Itn 0 -- Feasible QP solution.
 1 7.5E-01 0 -4.375000E+00 3.5E-01
 2 1.0E+00 0 -4.400000E+00 0.0E+00
 3 1.9E-01 0 -4.700000E+00 1.6E+00
 4 1.0E+00 0 -5.100000E+00 2.2E-16
 Itn 5 -- Hessian numerically indefinite.
 Square of diag, min diag = -1.4E-14 2.7E-13.
 5 2.2E-01 0 -5.932500E+00 3.7E+00
 6 4.7E-01 0 -6.179688E+00 1.1E+00
 7 1.0E+00 0 -6.267162E+00 2.2E-16
 8 8.1E-03 0 -6.532489E+00 1.4E+00
 9 6.3E-01 0 -7.583236E+00 1.3E-15
 10 1.0E+00 0 -8.067718E+00 8.9E-16
 11 1.0E+00 0 -8.067778E+00 2.2E-16

Variable State	Value	Lower Bound	Upper Bound	Lagr Mult	Residual
...X1... UL	2.00000	-2.0000	2.0000	-0.8000	.
...X2... SBS	-0.233333	-2.0000	2.0000	.	1.767
...X3... SBS	-0.266667	-2.0000	2.0000	.	1.733
...X4... BS	-0.300000	-2.0000	2.0000	.	1.700
...X5... SBS	-1.000000E-01	-2.0000	2.0000	-1.5701E-16	1.900
...X6... UL	2.00000	-2.0000	2.0000	-0.9000	.
...X7... UL	2.00000	-2.0000	2.0000	-0.9000	.
...X8... SBS	-1.77778	-2.0000	2.0000	1.7612E-17	0.2222
...X9... BS	-0.455556	-2.0000	2.0000	-5.5511E-17	1.544

Constrnt State	Value	Lower Bound	Upper Bound	Lagr Mult	Residual
..ROW1.. UL	1.50000	-2.0000	1.5000	-6.6667E-02	.
..ROW2.. UL	1.50000	-2.0000	1.5000	-3.3333E-02	.
..ROW3.. BS	3.93333	-2.0000	4.0000	.	-6.6667E-02
..COST.. BS	-10.7856	None	None	-1.000	-10.79

Finished the E04NDF example.

Exit E04NKF - Optimal QP solution found.

Final QP objective value = -8.067778

Exit from QP problem after 11 iterations.